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RELAXED MULTI-MARGINAL COSTS AND QUANTIZATION EFFECTS

GUY BOUCHITTÉ, GIUSEPPE BUTTAZZO, THIERRY CHAMPION, LUIGI DE PASCALE

ABSTRACT. We propose a duality theory for multi-marginal repulsive cost that appears in optimal transport problems arising in Density Functional Theory. The related optimization problems involve probabilities on the entire space and, as minimizing sequences may lose mass at infinity, it is natural to expect relaxed solutions which are sub-probabilities. We first characterize the N -marginals relaxed cost in terms of a stratification formula which takes into account all k interactions with $k \leq N$. We then develop a duality framework involving continuous functions vanishing at infinity and deduce primal-dual necessary and sufficient optimality conditions. Next we prove the existence and the regularity of an optimal dual potential under very mild assumptions. In the last part of the paper, we apply our results to a minimization problem involving a given continuous potential and we give evidence of a mass quantization effect for optimal solutions.

Keywords: Multi-marginal optimal transport, Duality and Relaxation, Coulomb cost, Quantization of minimizers

2010 Mathematics Subject Classification: 49J45, 49N15, 49K30, 35Q40

1. INTRODUCTION

An interesting issue in *Density Functional Theory* (DFT), an important branch of Quantum Chemistry, is to understand the asymptotic behavior as $\varepsilon \rightarrow 0$ of the infimum problem

$$\min \{ \varepsilon T(\rho) + C(\rho) - U(\rho) : \rho \in \mathcal{P} \} \quad (1.1)$$

where ε is a small parameter which depends on the Planck constant and

- $T(\rho)$ is the kinetic energy

$$T(\rho) = \int_{\mathbb{R}^d} |\nabla \sqrt{\rho}|^2 dx;$$

- $C(\rho)$ describes the electron-electron interaction;
- $U(\rho)$ is the potential term

$$U(\rho) = \int_{\mathbb{R}^d} V(x)\rho dx;$$

- \mathcal{P} is the class of all probabilities over \mathbb{R}^d .

The term $C(\rho)$ is the one on which we focus our attention. Here we want to stress that the ambient space is the whole \mathbb{R}^d ($d = 3$ in the physical applications); for simplicity integrals over \mathbb{R}^d are often denoted without the indication of the domain of integration, and similarly for spaces of functions or measures defined over all \mathbb{R}^d we do not indicate the domain. Starting from the works [5] and [8] the link between optimal transportation problems [24] and DFT for Coulomb systems [19] has been

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investigated and in particular the term $C(\rho)$ has been considered as a multi-marginal transport cost:

$$C(\rho) = \inf \left\{ \int_{\mathbb{R}^{Nd}} c(x_1, \dots, x_N) dP : P \in \Pi(\rho) \right\}$$

where

$$c(x_1, \dots, x_N) = \sum_{1 \leq i < j \leq N} \frac{1}{|x_i - x_j|}$$

and $\Pi(\rho)$ is the family of multi-marginal transport plans

$$\Pi(\rho) = \{P \in \mathcal{P}(\mathbb{R}^{Nd}) : \pi_i^\# P = \rho \text{ for all } i = 1, \dots, N\}$$

being π_i the projections from \mathbb{R}^{Nd} on the i -th factor \mathbb{R}^d and $\pi_i^\#$ the push-forward operator

$$\pi_i^\# P(E) = P(\pi_i^{-1}(E)) \quad \text{for all Borel sets } E \subset \mathbb{R}^d.$$

The relationship of the transport cost $C(\rho)$ with the DFT is mainly related to the fact that it is the semiclassical limit of the Levy-Lieb energy as shown in [2, 8, 9, 17].

If U is associated with a Coulomb potential $V : \mathbb{R}^d \rightarrow [0, +\infty]$ of the kind

$$V(x) = \sum_{k=1}^M \frac{Z_k}{|x - X_k|} \quad Z_k > 0, X_k \in \mathbb{R}^d,$$

where for $k = 1, \dots, M$ the X_k are the positions of the nuclei and Z_k the corresponding charges, it turns out that the infimum in (1.1) blows up to $-\infty$ as ε^{-1} . Studying the rescaled problem as $\varepsilon \rightarrow 0$ is quite a difficult issue due to the presence of the strong interaction term $C(\rho)$. In particular it is not clear under which conditions on the potential V the problem (1.1) admits a solution and what is the limiting problem as $\varepsilon \rightarrow 0$ in the sense of Γ -convergence. A partial answer is known when the electronic energy $C(\rho)$ involves two electrons only (see [3]). Some theoretical and numerical results on the same problem are also contained in [6].

In contrast, if instead of the Coulomb potential we choose a continuous potential V vanishing at infinity, then the infimum in (1.1) remains bounded as $\varepsilon \rightarrow 0$. It is important to notice that limits of minimizing sequences (ρ_ε) are not in general probabilities since some mass can be lost at infinity (what we call *ionization* phenomenon [13, 14, 22, 23]). It turns out by an elementary Γ -convergence argument that, in this case, the weak* limits of (ρ_ε) can be characterized as solutions of the limit problem

$$\min \left\{ \bar{C}(\rho) - \int V d\rho : \rho \in \mathcal{P}^- \right\} \quad (1.2)$$

where $\bar{C}(\rho)$ is the relaxation of the functional $C(\rho)$ defined by:

$$\bar{C}(\rho) = \inf \left\{ \liminf_n C(\rho_n) : \rho_n \xrightarrow{*} \rho, \rho_n \in \mathcal{P} \right\}.$$

Notice that $\bar{C}(\rho)$ is defined for all ρ belonging to the class of sub-probabilities

$$\mathcal{P}^- = \{ \rho \text{ nonnegative Borel regular measure on } \mathbb{R}^d : \|\rho\| \leq 1 \}$$

where by $\|\rho\|$ we simply denoted the mass of ρ

$$\|\rho\| = \int d\rho.$$

The minimization problem (1.2) is convex and our first goal is to develop a duality theory for the optimal transport problem related to the cost functional $\overline{C}(\rho)$. This is achieved by considering the compactification of \mathbb{R}^d through the addition of a point ω at infinity and the related dual space $C_0 \oplus \mathbb{R}$, where by C_0 we denote the space of continuous functions on \mathbb{R}^d vanishing at infinity. The duality formula is illustrated in Theorem 3.2:

$$\overline{C}(\rho) = \sup \left\{ \int \psi d\rho + (1 - \|\rho\|)\psi_\infty : \psi \in \mathcal{A} \right\} \quad (1.3)$$

where \mathcal{A} is the class of admissible functions, defined as

$$\mathcal{A} = \left\{ \psi \in C_0 \oplus \mathbb{R} : \frac{1}{N} \sum_{i=1}^N \psi(x_i) \leq c(x_1, \dots, x_N) \quad \forall x_i \in (\mathbb{R}^d)^N \right\},$$

and ψ_∞ denotes the limit of ψ at infinity. Furthermore we prove for a large class of ρ the existence of an optimal Lipschitz continuous potential ψ for (1.3). We are also able to represent the relaxed cost functional \overline{C} through a *stratification* formula:

$$\overline{C}(\rho) = \inf \left\{ \sum_{k=1}^N \mathcal{C}_k(\rho_k) : \rho_k \in \mathcal{P}^-, \sum_{k=1}^N \frac{k}{N} \rho_k = \rho, \sum_{k=1}^N \|\rho_k\| \leq 1 \right\} \quad (1.4)$$

which makes use of all *partial interaction functionals* $\mathcal{C}_k, 1 \leq k \leq N$ as defined in (2.5).

As an application of our duality theory we analyze the optimization problem (1.2) with a potential $V(x)$ belonging to C_0 . Even in this simplified case, when no kinetic energy is present, we discover a very rich and surprising structure in which, depending on the choice of V , we obtain optimal solutions which are either probabilities or sub-probabilities with fractional mass $\frac{k}{N}$ with k integer (phenomenon that we may interpret as a *mass quantization effect*).

Most of the results presented in this paper could be extended with little effort to the more general case of an interaction cost of the form

$$c(x_1, \dots, x_N) = \sum_{1 \leq i < j \leq N} \ell(|x_i - x_j|),$$

where the function $\ell : \mathbb{R}^+ \rightarrow (0, +\infty]$ is lower semicontinuous and vanishes at infinity. Some more technical requirements on the function ℓ are needed to extend the existence and Lipschitz regularity result of Section 4.

The structure of the paper is as follow. In Section 2, we first identify the relaxed functional $\overline{C}(\rho)$ on \mathcal{P}^- in an abstract compact framework (Proposition 2.2) and then establish the representation formula (1.4). In Section 3, we develop a complete duality framework extending previous works [4, 11, 15] to the case of sub-probabilities and allowing practical computations in case of finitely supported measures (Proposition 3.8). In addition we derive some very useful primal-dual necessary and sufficient optimality conditions (Theorem 3.12). The long Section 4 is devoted to the existence and Lipschitz regularity of an optimal dual potential for sub-probabilities. In Section 5, we apply all previous results to the relaxed problem (1.2) and highlight the mass quantization effect.

Before concluding this introduction, some comments are in order. Surprisingly, it seems that the relaxation issue for the N -multi marginal cost has never been studied before, although it appears naturally in DFT theory, namely for existence

or non existence issues (*ionization phenomenon*) and also when dealing with related asymptotic problems as in [3]. Let us point out that the study of the asymptotic limit of N particles as $N \rightarrow \infty$ in the framework of *Grand Canonical Theory* leads to use representation formulae quite similar to (1.4) (see for instance [16, 20, 21]). We recently became aware that some results making a connection between our relaxation approach and Grand Canonical Optimal Transportation are currently being obtained by Di Marino, Lewin and Nenna [12].

Let us list some notation that will be used constantly along the paper.

- C_b is the space of continuous and bounded functions in \mathbb{R}^d equipped with the sup-norm;
- C_0 is the separable Banach subspace of C_b consisting of those functions vanishing at ∞ and C_0^+ is subclass of nonnegative elements of C_0 ;
- \mathcal{M}_b is the space of bounded Borel regular measures (dual of C_0), and \mathcal{M}_b^+ is the subclass of nonnegative elements of \mathcal{M}_b ;
- Lip is the space of Lipschitz continuous functions on \mathbb{R}^d and for an element $\varphi \in Lip$ the Lipschitz semi-norm will be denoted by $Lip(\varphi)$. Lip_k is the subset of Lipschitz functions with Lipschitz constant lower or equal than k ;
- ψ_+ denotes the positive part of a function ψ , i.e. $\max\{\psi, 0\}$;
- $\mathcal{P}(E)$ is the set of Borel regular probability measures on the metric space E ;
- $\mathcal{P}^-(E)$ is the set of Borel regular sub-probability measures on the metric space E , i.e. the set of nonnegative measures ρ of total variation $\|\rho\| \leq 1$. \mathcal{P}^- will be equipped with the weak* convergence. With this convergence \mathcal{P}^- is a compact metrizable space.

2. THE RELAXED MULTI-MARGINAL COST

A crucial step for the proof of the existence of an optimal $\rho \in \mathcal{P}$ for the minimization problem (1.2) is the study of the relaxed cost

$$\bar{C}(\rho) = \inf \left\{ \liminf_n C(\rho_n) : \rho_n \xrightarrow{*} \rho, \rho_n \in \mathcal{P} \right\}$$

of the electron-electron interaction functional $C(\rho)$. Note that, while $C(\rho)$ is defined on probabilities $\rho \in \mathcal{P}$, since the weak* convergence may allow loss of mass at infinity, the relaxed cost $\bar{C}(\rho)$ is defined for $\rho \in \mathcal{P}^-$. The complete characterization of $C(\rho)$ is obtained in Subsection 2.2. In a first step we derive $\bar{C}(\rho)$ in a abstract way by embedding \mathbb{R}^d into its Alexandroff compactification.

2.1. A compact framework for the relaxed cost. It is convenient to study this cost in a compact framework, by embedding the elements $\rho \in \mathcal{P}^-$ as probabilities in a compact space. To this end, we introduce a point ω at infinity, and we denote by $X = \mathbb{R}^d \cup \{\omega\}$ the compact set resulting from Alexandrov's construction. We also denote $S : x \mapsto x$ the identity embedding of \mathbb{R}^d into X , and consider the transformed Coulomb cost \tilde{c} on X^N given by

$$\tilde{c}(x_1, \dots, x_N) = \sum_{1 \leq i < j \leq N} \frac{1}{|x_i - x_j|} \quad (2.1)$$

where we set $1/|a - b| = 0$ whenever a or b equals ω . Note that this convention yields that \tilde{c} is lower semi-continuous on X . We can now define the transport cost

\tilde{C} for any $\tilde{\rho} \in \mathcal{P}(X)$ by

$$\tilde{C}(\tilde{\rho}) := \min \left\{ \int_{X^N} \tilde{c} d\tilde{P} : \tilde{P} \in \mathcal{P}(X^N), \tilde{P} \in \Pi(\tilde{\rho}) \right\}. \quad (2.2)$$

The existence of the minimum in (2.2) follows from the lower semicontinuity of $\tilde{P} \mapsto \int_{X^N} \tilde{c} d\tilde{P}$ and the compactness of $\Pi(\tilde{\rho})$ with respect to the narrow convergence on $\mathcal{P}(X^N)$. In addition, it can be checked that $\tilde{\rho} \mapsto \tilde{C}(\tilde{\rho})$ is lower semi-continuous on $\mathcal{P}(X)$ endowed with the narrow convergence.

Remark 2.1. In the following, we shall often use the fact that there exists at least one *symmetric* optimal solution \tilde{P} for $\tilde{C}(\tilde{\rho})$, that is $\tilde{P} = \sigma^\# \tilde{P}$ for any permutation $\sigma \in \mathcal{S}_N$. Here, to any permutation $\sigma \in \mathcal{S}_N$ we associate (with some abuse of notation) the function $\sigma : X^N \rightarrow X^N$ given by

$$\sigma((x_1, \dots, x_N)) = (x_{\sigma(1)}, \dots, x_{\sigma(N)}).$$

The existence of such a symmetric solution \tilde{P} follows by symmetrization: to a solution \tilde{P}' of (2.2) we can associate the symmetric plan

$$\tilde{P} = \frac{1}{N!} \sum_{\sigma \in \mathcal{S}_N} \sigma^\# \tilde{P}'$$

which is itself an optimal solution since the cost \tilde{c} is symmetric (meaning here that $\tilde{c} \circ \sigma = \tilde{c}$ for any $\sigma \in \mathcal{S}_N$).

The relation between C and \tilde{C} is as follows: for $\rho \in \mathcal{P}$ we have that $\tilde{\rho} := S^\# \rho$ belongs to $\mathcal{P}(X)$, and

$$P \in \Pi(\rho) \iff \tilde{P} := (S^{\otimes N})^\# P \in \Pi(\tilde{\rho})$$

where we use the notation $f^{\otimes N} = f \otimes \dots \otimes f$ (N times). With this notation we have

$$\int_{(\mathbb{R}^d)^N} c dP = \int_{X^N} \tilde{c} d\tilde{P}.$$

As a consequence $C(\rho) = \tilde{C}(S^\# \rho)$ whenever $\rho \in \mathcal{P}$. The following result now relates \bar{C} and \tilde{C} .

Proposition 2.2. *For every $\rho \in \mathcal{P}^-$ it holds*

$$\bar{C}(\rho) = \tilde{C}(\tilde{\rho}) \quad \text{for } \tilde{\rho} := S^\# \rho + (1 - \|\rho\|)\delta_\omega. \quad (2.3)$$

Proof. We denote by

$$\Gamma(\rho) := \tilde{C}(S^\# \rho + (1 - \|\rho\|)\delta_\omega)$$

the right hand side of (2.3). From the preceding discussion we clearly have

$$\bar{C}(\rho) = C(\rho) = \Gamma(\rho) \quad \text{whenever } \rho \in \mathcal{P}.$$

We first claim that Γ is weakly* lower semicontinuous on \mathcal{P}^- . Indeed, assume that $\rho_n \xrightarrow{*} \rho$ in \mathcal{P}^- , and consider the probabilities over X

$$\tilde{\rho}_n = S^\# \rho_n + (1 - \|\rho_n\|)\delta_\omega.$$

Then the sequence $(\tilde{\rho}_n)_n$ is weakly* compact in $\mathcal{P}(X)$ so that $\tilde{\rho}_n \xrightarrow{*} \tilde{\rho}$ for some $\tilde{\rho} \in \mathcal{P}(X)$. We then infer $\tilde{\rho} \ll \mathbb{R}^d = \rho$, so that in fact $\tilde{\rho} = S^\# \rho + (1 - \|\rho\|)\delta_\omega$ and

$$\liminf_n \Gamma(\rho_n) = \liminf_n \tilde{C}(\tilde{\rho}_n) \geq \tilde{C}(\tilde{\rho}) = \Gamma(\rho).$$

This proves the claim. Since \bar{C} is the largest weakly* lower semicontinuous functional on \mathcal{P}^- which is lower than C on \mathcal{P} , we conclude that $\bar{C} \geq \Gamma$.

We now turn to the opposite inequality $\bar{C} \leq \Gamma$. Let $\rho \in \mathcal{P}^-$, fix $\tilde{\rho} := S^\# \rho + (1 - \|\rho\|)\delta_\omega$ and $\tilde{P} \in \Pi(\tilde{\rho})$ a symmetric plan (see Remark 2.1) such that

$$\Gamma(\rho) = \tilde{C}(\tilde{\rho}) = \int_{X^N} \tilde{c} d\tilde{P}.$$

We fix N distinct vectors ξ_1, \dots, ξ_N on the unit sphere \mathbb{R}^d , and for any integer n we define the Borel map $h_n : X^N \rightarrow (\mathbb{R}^d)^N$ by

$$h_n(x_1, \dots, x_N) = (h_{n,1}(x_1), \dots, h_{n,N}(x_N))$$

where $h_{n,i} : X \rightarrow \mathbb{R}^d$ is given by

$$h_{n,i}(x) = \begin{cases} x & \text{if } x \in B(0, n), \\ 2n\xi_i & \text{otherwise.} \end{cases}$$

Note that on X^N it holds

$$c \circ h_n \leq \tilde{c} + \frac{N(N-1)}{2} \max_{i \neq j} \left\{ \frac{1}{n}, \frac{1}{2n|\xi_i - \xi_j|} \right\} = \tilde{c} + O\left(\frac{1}{n}\right). \quad (2.4)$$

We now define P_n as the symmetrization of $(h_n)^\# \tilde{P}$, that is

$$P_n = \frac{1}{N!} \sum_{\sigma \in \mathcal{S}_N} \sigma^\#((h_n)^\# \tilde{P})$$

We denote by ρ_n the marginal of P_n , then $\rho_n \in \mathcal{P}$ satisfies $\rho_n \llcorner B(0, n) = \rho \llcorner B(0, n)$. As a consequence we get $\rho_n \xrightarrow{*} \rho$, so that from (2.4) we have

$$\begin{aligned} \bar{C}(\rho) &\leq \liminf_n C(\rho_n) \leq \liminf_n \int_{(\mathbb{R}^d)^N} c dP_n \\ &= \liminf_n \int_{X^N} c \circ h_n d\tilde{P} \\ &\leq \int_{X^N} \tilde{c} d\tilde{P} = \Gamma(\rho), \end{aligned}$$

which concludes the proof. \square

2.2. Stratified representation of the relaxed cost. The formula (2.3) in Proposition 2.2 allows to recover the representation formula obtained in the case $N = 2$ in [3, Proposition 2.5] and to generalize it to any value $N \geq 2$. To this end, we must reinterpret an optimal \tilde{P} for (2.2) by splitting it via its restrictions to all subsets of the kind $(\mathbb{R}^d)^k \times \{\omega\}^{N-k}$ (with $2 \leq k \leq N$), each of which accounts for interactions between only k electrons, the $N - k$ remaining being at infinity. Accordingly introduce all partial correlation costs \mathcal{C}_k involving interactions k electrons interactions for $2 \leq k \leq N$. They are defined by setting for any $\mu \in \mathcal{P}^-$:

$$\mathcal{C}_k(\mu) := \inf \left\{ \int_{(\mathbb{R}^d)^N} c_k(x_1, \dots, x_k) dP(x_1, \dots, x_k) : \pi_i^\# P = \mu, \forall i = 1, \dots, k \right\} \quad (2.5)$$

where transport plans P are now nonnegative Borel regular measures on $(\mathbb{R}^d)^k$ with total mass $\|P\| = \|\mu\| = \int d\mu$ and

$$c_k(x_1, \dots, x_k) := \tilde{c}(x_1, \dots, x_k, \omega, \dots, \omega) = \sum_{1 \leq i < j \leq k} \frac{1}{|x_i - x_j|}, \quad (2.6)$$

being \tilde{c} defined by (2.1). It is also convenient to define \mathcal{C}_1 on \mathcal{P}^- as $\mathcal{C}_1 \equiv 0$ (meaning that no interaction exists for a single electron). Note that our initial multi-marginal cost $C(\rho)$ agrees with $\mathcal{C}_N(\rho)$ for $\rho \in \mathcal{P}$.

We are now in position to state our stratification representation result:

Theorem 2.3. *For every $\rho \in \mathcal{P}^-$ it holds*

$$\bar{C}(\rho) = \inf \left\{ \sum_{k=1}^N \mathcal{C}_k(\rho_k) : \rho_k \in \mathcal{P}^-, \sum_{k=1}^N \frac{k}{N} \rho_k = \rho, \sum_{k=1}^N \|\rho_k\| \leq 1 \right\}. \quad (2.7)$$

Moreover the infimum is attained whenever $\bar{C}(\rho) < +\infty$.

Remark 2.4. At this stage, we notice an important connection with the so-called *grand canonical* formulation for the infinite multi-marginal problem. Indeed, if we rewrite the sub-probabilities ρ_k in the form $\rho_k = \alpha_k \nu_k$ with $\|\nu_k\| = 1$ and $0 \leq \alpha_k \leq 1$, we obtain

$$\bar{C}(\rho) = \inf \left\{ \sum_{k=1}^N \alpha_k \frac{k}{N} \mathcal{C}_k(\nu_k) : \nu_k \in \mathcal{P}, \sum_{k=1}^N \alpha_k \frac{k}{N} \nu_k = \rho, \sum_{k=1}^N \alpha_k \leq 1 \right\}. \quad (2.8)$$

In the grand canonical formulation (see for instance [18]), the summation with respect to k in (2.8) runs from 0 to $+\infty$. Mixed formulations have been used as well by Cotar and Petrache (see [10]) and, very recently, by Di Marino, Lewin and Nenna [12]. In the present paper, we aim to emphasize the connection with the relaxation framework which is crucial for existence and nonexistence issues.

Remark 2.5. From the stratification formula (2.3), we deduce that, for $1 \leq k \leq N$, one has

$$\bar{C}(\rho) \leq \mathcal{C}_k \left(\frac{N\rho}{k} \right) \quad \text{whenever } \|\rho\| = \frac{k}{N} \quad (2.9)$$

This is a consequence of (2.7) when taking $\rho_k = N\rho/k$ and $\rho_j = 0$ if $j \neq k$. We conjecture that the inequality in (2.9) is in fact an equality (this would highlight the fact that configurations involving an integer number of electrons play a special role).

Proof of Theorem 2.3. Fix $\rho \in \mathcal{P}^-$ and consider the associated problem

$$(Q_\rho) \quad \inf \left\{ \sum_{k=1}^N \mathcal{C}_k(\rho_k) : \rho_k \in \mathcal{P}^-, \sum_{k=1}^N \frac{k}{N} \rho_k = \rho, \sum_{k=1}^N \|\rho_k\| \leq 1 \right\}.$$

We first claim that $\bar{C}(\rho) \geq \inf(Q_\rho)$, and assume without loss of generality that $\bar{C}(\rho) < +\infty$. By applying Proposition 2.2 to ρ , we may take $\tilde{P} \in \mathcal{P}(X^N)$ to be an optimal symmetric plan for $\tilde{C}(\tilde{\rho}) = \bar{C}(\rho)$ in the right hand side of (2.3). Then we set

$$\tilde{\mu}_k := \pi_1^\# \left(\tilde{P} \llcorner (\mathbb{R}^d)^k \times \{\omega\}^{N-k} \right) \quad \text{and} \quad \nu_k := \binom{N}{k} \tilde{\mu}_k \llcorner \mathbb{R}^d$$

for any k in $\{1, \dots, N\}$, with the convention $(\mathbb{R}^d)^N \times \{\omega\}^0 = (\mathbb{R}^d)^N$. By the symmetry of \tilde{P} , we have

$$\begin{aligned} 1 &= \int_{(\mathbb{R}^d \cup \{\omega\})^N} d\tilde{P} = \sum_{k=0}^N \binom{N}{k} \int_{(\mathbb{R}^d)^k \cup \{\omega\}^{N-k}} d\tilde{P} \\ &\geq \sum_{k=1}^N \binom{N}{k} \int_{\mathbb{R}^d} d\tilde{\mu}_k = \sum_{k=1}^N \|\nu_k\|, \end{aligned}$$

and

$$\pi_1^\# \left(\tilde{P} \llcorner (\mathbb{R}^d \times X^{N-1}) \right) = \pi_1^\# \left(\tilde{P} \llcorner (\mathbb{R}^d \times (\mathbb{R}^d \cup \{\omega\})^{N-1}) \right) = \sum_{k=1}^N \binom{N-1}{k-1} \tilde{\mu}_k,$$

where the binomial coefficients come by developing the product spaces $(\mathbb{R}^d \cup \{\omega\})^N$ and $(\mathbb{R}^d \cup \{\omega\})^{N-1}$ respectively. Since $\pi_1^\# \tilde{P} = \tilde{\rho} = S^\# \rho + (1 - \|\rho\|) \delta_\omega$, we then infer

$$\rho = \sum_{k=1}^N \binom{N-1}{k-1} \tilde{\mu}_k \llcorner \mathbb{R}^d = \sum_{k=1}^N \frac{k}{N} \nu_k.$$

As a consequence, the measures ν_k satisfy the constraints of (Q_ρ) . Using the symmetry of \tilde{c} and \tilde{P} and the definition of c_k in (2.6), we obtain

$$\bar{C}(\rho) = \sum_{k=2}^N \binom{N}{k} \int_{(\mathbb{R}^d)^k \times \{\omega\}^{N-k}} \tilde{c} d\tilde{P} = \sum_{k=2}^N \int_{(\mathbb{R}^d)^k} c_k dP_k$$

where for each $k \geq 2$, we indicate by P_k the Borel sub-probability on $(\mathbb{R}^d)^k$

$$P_k := \binom{N}{k} \pi_{1, \dots, k}^\# \tilde{P}$$

being $\pi_{1, \dots, k} : (\mathbb{R}^d)^N \rightarrow (\mathbb{R}^d)^k$ the projection on the k first copies of \mathbb{R}^d . Then for any k the transport plan P_k has marginals ν_k so that

$$\bar{C}(\rho) = \sum_{k=2}^N \int_{(\mathbb{R}^d)^k} c_k dP_k \geq \sum_{k=2}^N \mathcal{C}_k(\nu_k) \geq \inf(Q_\rho)$$

which proves the claim. Note that, under the hypothesis $\bar{C}(\rho) < +\infty$, the equality $\bar{C}(\rho) = \inf(Q_\rho)$ would directly yield that the family ν_2, \dots, ν_N is a solution of (Q_ρ) .

We now prove the reverse inequality $\bar{C}(\rho) \leq \inf(Q_\rho)$, and assume without loss of generality that $\inf(Q_\rho) < +\infty$. We consider ρ_1, \dots, ρ_N admissible for (Q_ρ) such that $\sum_{k=1}^N \mathcal{C}_k(\rho_k) < +\infty$. For each $k \geq 2$ take $P_k \in \mathcal{P}^-((\mathbb{R}^d)^k)$ symmetric and optimal for $\mathcal{C}_k(\rho_k)$, we also set $P_1 = \rho_1$ and define for $k \geq 1$ the plans

$$\tilde{P}_k := \left((S^{\otimes k})^\# P_k \right) \otimes \overbrace{\delta_\omega \otimes \dots \otimes \delta_\omega}^{N-k \text{ times}}.$$

We now symmetrize the plans \tilde{P}_k in the following way : for any $k \in \{1, \dots, N\}$ we define

$$\text{Sym}(\tilde{P}_k) := \binom{N}{k}^{-1} \sum_{I \subset \{1, \dots, N\}, |I|=k} (\sigma_I)^\# \tilde{P}_k$$

where σ_I is the permutation of $\{1, \dots, N\}$ given by

$$m \in \{1, \dots, N\} \mapsto \sigma_I(m) = \begin{cases} i_m & \text{whenever } m \in \{1, \dots, k\} \\ j_m & \text{whenever } m \in \{k+1, \dots, N\} \end{cases}$$

where $i_1 < \dots < i_k$ and $j_{k+1} < \dots < j_N$ denote respectively the elements of I and $\{1, \dots, N\} \setminus I$ in increasing order. Eventually we set

$$\tilde{P}^* := \sum_{k=1}^N \text{Sym}(\tilde{P}_k)$$

and we note that \tilde{P}^* is a sub-probability on X^N since

$$\int_{X^N} d\tilde{P}^* = \sum_{k=1}^N \int_{X^N} d\tilde{P}_k = \sum_{k=1}^N \|P_k\| = \sum_{k=1}^N \|\rho_k\| \leq 1$$

where the last inequality follows from the constraint in (Q_ρ) . We can then define on X^N the probability

$$\tilde{P} = \tilde{P}^* + (1 - \|\tilde{P}^*\|)\delta_\omega \otimes \dots \otimes \delta_\omega.$$

We now compute the first marginal $\tilde{\rho} = \pi_1^\# \tilde{P}$: since it is a probability over X it is sufficient to consider its restriction to \mathbb{R}^d , which gives

$$\begin{aligned} \tilde{\rho} \llcorner \mathbb{R}^d &= \sum_{k=1}^N \binom{N}{k}^{-1} \sum_{I \subset \{1, \dots, N\}, |I|=k} \pi_1^\# \left((\sigma_I)^\# \tilde{P}_k \right) \llcorner \mathbb{R}^d \\ &= \sum_{k=1}^N \binom{N}{k}^{-1} \binom{N-1}{k-1} \rho_k = \sum_{k=1}^N \frac{k}{N} \rho_k = \rho \end{aligned}$$

where we used the fact that

$$\pi_1^\# \left((\sigma_I)^\# \tilde{P}_k \right) \llcorner \mathbb{R}^d = 0 \quad \text{whenever } 1 \notin I.$$

As a consequence $\tilde{\rho} = S^\# \rho + (1 - \|\rho\|)\delta_\omega$. We now infer from (2.3) that

$$\bar{C}(\rho) = \tilde{C}(\tilde{\rho}) \leq \int_{X^N} \tilde{c} d\tilde{P} = \sum_{k=1}^N \int_{X^N} \tilde{c} d\tilde{P}_k = \sum_{k=1}^N \mathcal{C}_k(\rho_k)$$

which concludes the proof. \square

We conclude this Section by a monotonicity formula for the partial interaction costs \mathcal{C}_k .

Proposition 2.6. *Let $\mu \in \mathcal{P}^-$, then it holds*

$$\forall k \geq l, \quad \mathcal{C}_k(\mu) \geq \frac{k(k-1)}{l(l-1)} \mathcal{C}_l(\mu).$$

In particular, one has

$$\forall k \geq 1, \quad \mathcal{C}_{k+1}(\mu) \geq \frac{k+1}{k-1} \mathcal{C}_k(\mu).$$

Proof. Without loss of generality we assume $\mathcal{C}_k(\mu) < +\infty$, and we denote by P_k a symmetric measure in $\Pi_k(\mu)$ such that

$$\mathcal{C}_k(\mu) = \int c_k dP_k.$$

We define the measures $P_2 := \pi_{1,2}^\# P_k$ and $P_l := \pi_{1,\dots,l}^\# P_k$ to be the push-forward of P_k by the projection on the 2 and l first spaces \mathbb{R}^d respectively. We note that these two measures have μ as marginals and that

$$\pi_{1,2}^\# P_l = \pi_{1,2}^\# P_k = P_2.$$

From the symmetry of P_k and P_l we can compute

$$\mathcal{C}_k(\mu) = \int c_k dP_k = \binom{k}{2} \int c_2 dP_2 \quad \text{and} \quad \binom{l}{2} \int c_2 dP_2 = \int c_l dP_l \geq \mathcal{C}_l(\mu)$$

from which the inequality follows. \square

3. DUAL FORMULATION OF THE RELAXED COST

This Section is devoted to a duality formula for $\overline{C}(\rho)$. We consider the separable Banach space $C_0 \oplus \mathbb{R}$ consisting of all continuous functions $\psi : \mathbb{R}^d \rightarrow \mathbb{R}$ with a constant value at infinity, that is of the form $\psi = \varphi + \kappa$ with $\varphi \in C_0$ and $\kappa \in \mathbb{R}$. Then we consider the closed convex subset

$$\mathcal{A} = \left\{ \psi \in C_0 \oplus \mathbb{R} : \frac{1}{N} \sum_{i=1}^N \psi(x_i) \leq c(x) \quad \forall x \in (\mathbb{R}^d)^N \right\}. \quad (3.1)$$

It is convenient to introduce also a larger convex set namely

$$\mathcal{B} = \left\{ \psi \in \mathcal{S} : \frac{1}{N} \sum_{i=1}^N \psi(x_i) \leq c(x) \quad \forall x \in (\mathbb{R}^d)^N \right\} \quad (3.2)$$

where \mathcal{S} denotes the set of lower semicontinuous functions $\psi : \mathbb{R}^d \rightarrow \mathbb{R}$ such that $\inf \psi > -\infty$. To any such a function ψ , we associate the real numbers

$$\psi_\infty := \liminf_{|x| \rightarrow +\infty} \psi(x) = \lim_{R \rightarrow +\infty} \left(\inf \{ \psi(x) : |x| \geq R \} \right),$$

$$\psi^\infty := \limsup_{|x| \rightarrow +\infty} \psi(x) = \lim_{R \rightarrow +\infty} \left(\sup \{ \psi(x) : |x| \geq R \} \right).$$

By induction on the integer N , it is easy to check that

$$\psi^\infty \leq 0 \quad \text{for every } \psi \in \mathcal{B}.$$

A particular choice of such a function in \mathcal{B} is provided in Example 3.6 hereafter. We will use the following truncation lemma.

Lemma 3.1. *Let ψ belong to \mathcal{A} (resp. to \mathcal{B}) and let $\lambda \leq \psi^\infty$. Then the function $\psi_\lambda := \max\{\psi, \lambda\}$ also belongs to \mathcal{A} (resp. to \mathcal{B}).*

Proof. We have only to check that ψ_λ still satisfies the inequality constraint appearing in the definitions of \mathcal{A} and \mathcal{B} . Let $(x_1, \dots, x_N) \in (\mathbb{R}^d)^N$ and set $I = \{i : \psi_\lambda(x_i) = \lambda\}$. Then consider sequences $(y_i^n)_n$ such that

$$|y_i^n| \rightarrow +\infty, \quad \lim_{n \rightarrow \infty} \psi(y_i^n) \geq \lambda, \quad |y_i^n - y_j^n| \rightarrow +\infty \text{ whenever } i \neq j.$$

Then we have

$$\begin{aligned} \frac{1}{N} \sum_{i=1}^N \psi_\lambda(x_i) &\leq \lim_{n \rightarrow +\infty} \frac{1}{N} \left(\sum_{i \in I} \psi(y_i^n) + \sum_{j \notin I} \psi(x_j) \right) \\ &\leq \lim_{n \rightarrow +\infty} c((y_i^n)_{i \in I}, (x_j)_{j \notin I}) \leq c(x) \end{aligned}$$

where, in the second inequality, we used the fact that all the terms $1/|y_i^n - y_j^n|$ and $1/|x_j - y_i^n|$ vanish as $n \rightarrow \infty$. \square

An important result is the following duality representation of $\bar{C}(\rho)$ which extends to the case $\|\rho\| < 1$ the formula obtained in [4] for $\|\rho\| = 1$.

Theorem 3.2. *For every $\rho \in \mathcal{P}^-$, the following equalities hold*

$$\bar{C}(\rho) = \sup_{\psi \in \mathcal{A}} \left\{ \int \psi d\rho + (1 - \|\rho\|)\psi_\infty \right\} = \sup_{\psi \in \mathcal{B}} \left\{ \int \psi d\rho + (1 - \|\rho\|)\psi_\infty \right\}, \quad (3.3)$$

where the classes \mathcal{A} and \mathcal{B} are defined in (3.1) and (3.2).

Remark 3.3. By Lemma 3.1, the two equalities in (3.3) are still valid if we restrict the supremum to those functions ψ such that $\psi \geq \psi_\infty = \psi^\infty$. This can be easily checked by substituting an admissible ψ by the function $\varphi = \max\{\psi, \psi^\infty\}$ which is still admissible with a larger energy, and for which it holds $\varphi_\infty = \varphi^\infty$.

Corollary 3.4. *Let ρ_1, ρ_2 in \mathcal{P}^- such that $\rho_1 \leq \rho_2$. Then $\bar{C}(\rho_1) \leq \bar{C}(\rho_2)$.*

Proof. Let us rewrite (3.3) as

$$\bar{C}(\rho) = \sup_{\psi \in \mathcal{A}} \left\{ \int (\psi - \psi_\infty) d\rho + \psi_\infty \right\}.$$

In view of Remark 3.3, we may assume that $\psi - \psi_\infty \geq 0$ from which the desired inequality follows. \square

Remark 3.5. In view of the compactification procedure introduced in Section 2, we may extend any function $\psi \in \mathcal{S}$ to $X = \mathbb{R}^d \cup \{\omega\}$ by setting $u = \psi$ on \mathbb{R}^d and $u(\omega) = \psi_\infty$. Notice that, by construction, u is lower semicontinuous as a function on X (i.e. $u \in \mathcal{S}(X)$) and that it is continuous if and only if $\psi_\infty = \lim_{|x| \rightarrow \infty} \psi(x)$ that is to say $\psi \in C_0 \oplus \mathbb{R}^d$. Furthermore, the point-wise constraint for $\psi \in \mathcal{B}$ is equivalent in term of u to the following

$$\frac{1}{N} \sum_{i=1}^{i=N} u(x_i) \leq \tilde{c}(x_1, x_2, \dots, x_N) \quad \forall x \in X^N, \quad (3.4)$$

being the extended cost \tilde{c} defined by (2.1). Accordingly, if $\rho \in \mathcal{P}^-$, the representation formula (3.3) can be rewritten as

$$\bar{C}(\rho) = \sup \left\{ \int_X u d\tilde{\rho} : u \in \mathcal{S}(X) \text{ satisfies (3.4)} \right\},$$

where the supremum is taken alternatively in $C(X)$ or in $\mathcal{S}(X)$ and $\tilde{\rho} := \rho + (1 - \|\rho\|)\delta_\omega$ denotes the probability measure on X defined by

$$\int_X u d\tilde{\rho} := \int u d\rho + (1 - \|\rho\|)u(\omega) = \int u d\rho + (1 - \|\rho\|)u_\infty.$$

Let us finally notice the following equivalence for a sequence (ρ_n) in \mathcal{P} and $\rho \in \mathcal{P}^-$:

$$\rho_n \xrightarrow{*} \rho \iff \rho_n \rightarrow \tilde{\rho} \text{ tightly on } X.$$

Proof of Theorem 3.2. For every pair $(\rho, \alpha) \in \mathcal{M}_b \times \mathbb{R}$, we set

$$H(\rho, \alpha) := \begin{cases} \alpha C(\rho/\alpha) & \text{if } \rho \geq 0, \alpha \in \mathbb{R}^+ \text{ and } \|\rho\| = \alpha, \\ +\infty & \text{otherwise.} \end{cases}$$

As C is convex proper and nonnegative on probability measures, it is easy to check that H is still convex proper nonnegative. In addition it is positively one homogeneous. Therefore the lower semicontinuous envelope of H on $\mathcal{M}_b \times \mathbb{R}$ endowed with its weak star topology can be characterized as the bipolar of H with respect to the duality between $\mathcal{M}_b \times \mathbb{R}$ and $C_0 \times \mathbb{R}$, namely

$$\begin{aligned} \overline{H}(\rho, \alpha) &= \sup \left\{ \int \varphi d\rho + \alpha\beta - H^*(\varphi, \beta) \right\} \\ &= \sup \left\{ \int \varphi d\rho + \alpha\beta : H^*(\varphi, \beta) \leq 0 \right\} \end{aligned} \quad (3.5)$$

where the supremum is taken over pairs $(\varphi, \beta) \in C^0 \times \mathbb{R}$ and where in the second equality we exploit the homogeneity of H . By the definition of H , we infer that:

$$H^*(\varphi, \beta) \leq 0 \iff \int \varphi d\rho + \beta \leq C(\rho) \quad \forall \rho \in \mathcal{P}.$$

By the definition of $C(\rho)$, the later inequality is equivalent to

$$\frac{1}{N} \int_{\mathbb{R}^{Nd}} \sum_{i=1}^N \varphi(x_i) dP + \beta \leq \int_{\mathbb{R}^{Nd}} c(x) P(dx) \quad \forall P \in \mathcal{P}.$$

By taking for P a Dirac mass, we may conclude that

$$H^*(\varphi, \beta) \leq 0 \iff \frac{1}{N} \sum_{i=1}^N \varphi(x_i) + \beta \leq c(x) \quad \forall x \in \mathbb{R}^{Nd}.$$

Therefore, setting $\psi = \varphi + \beta$ (thus $\psi_\infty = \beta$) and $\alpha = 1$, we deduce from (3.1) and (3.5) that

$$\overline{H}(\rho, 1) = \sup_{\psi \in \mathcal{A}} \left\{ \int \psi d\rho + (1 - \|\rho\|)\psi_\infty \right\}.$$

Therefore to establish the first equality in (3.3), we are reduced to show that:

$$\overline{C}(\rho) = \overline{H}(\rho, 1), \quad \forall \rho \in \mathcal{P}^- \quad (3.6)$$

The lower bound inequality for $\overline{C}(\rho)$ is straightforward since, for every sequence $\rho_n \xrightarrow{*} \rho$, it holds

$$\liminf_n C(\rho_n) = \liminf_n H(\rho_n, 1) \geq \overline{H}(\rho, 1).$$

To show that $\overline{C}(\rho) \leq \overline{H}(\rho, 1)$ for every $\rho \in \mathcal{P}^-$, we choose a particular sequence (ρ_n, α_n) in $\mathcal{M}_b^+ \times \mathbb{R}^+$ such that

$$\rho_n \xrightarrow{*} \rho, \quad \alpha_n \rightarrow 1, \quad H(\rho_n, \alpha_n) = \alpha_n C\left(\frac{\rho_n}{\alpha_n}\right) \rightarrow \overline{H}(\rho, 1).$$

Then, setting $\tilde{\rho}_n := \rho_n/\alpha_n$, we obtain a sequence of probability measures $(\tilde{\rho}_n)$ such that $\tilde{\rho}_n \xrightarrow{*} \rho$ and $C(\tilde{\rho}_n) \rightarrow \overline{H}(\rho, 1)$. Thus (3.6) is proved.

In order to prove the second equality in (3.3), since the subset \mathcal{B} is larger than \mathcal{A} , it is enough to show that

$$\overline{C}(\rho) \geq \int \psi d\rho + (1 - \|\rho\|)\psi_\infty, \quad \forall \psi \in \mathcal{B}, \forall \rho \in \mathcal{P}^-. \quad (3.7)$$

By (3.6), we know that the inequality above holds whenever ψ belongs to \mathcal{A} . To extend it to $\psi \in \mathcal{B}$, we follow Remark 3.5 considering the element of $\mathcal{S}(X)$ defined by $u = \psi$ on \mathbb{R}^d and $u(\omega) = \psi_\infty$. As X is a compact metrizable space, we can find a sequence (u_n) in $C^0(X)$ such that

$$u_{n+1} \geq u_n, \quad \sup_n u_n = u.$$

Clearly the restriction $\psi_n = u_n \llcorner \mathbb{R}^d$ satisfies $\psi_n \leq \psi$, thus belongs to \mathcal{A} . By applying Beppo Levi's theorem on X equipped with the probability measure $\tilde{\rho} = \rho + (1 - \|\rho\|)\delta_\omega$, we obtain:

$$\begin{aligned} \lim_n \int \psi_n d\rho + (1 - \|\rho\|)(\psi_n)_\infty &= \lim_n \int_X u_n d\tilde{\rho} \\ &= \int_X u d\tilde{\rho} = \int \psi d\rho + (1 - \|\rho\|)\psi_\infty, \end{aligned}$$

from which (3.7) follows. The proof of Theorem 3.2 is then achieved. \square

Example 3.6. Take for every $R > 0$

$$\psi_R(x) = \begin{cases} (N-1)/(4R) & \text{if } |x| < R, \\ -1/(4R) & \text{if } |x| \geq R. \end{cases}$$

It is easy to see that $\psi_R \in \mathcal{B}$; indeed, if x_1, \dots, x_k are in the ball $B_R(0)$ and x_{k+1}, \dots, x_N are in $\mathbb{R}^d \setminus B_R(0)$, we have to verify that

$$\frac{1}{N} \left(k \frac{N-1}{4R} - (N-k) \frac{1}{4R} \right) \leq \sum_{1 \leq i < j \leq N} \frac{1}{|x_i - x_j|}.$$

Now, the left-hand side above reduces to $(k-1)/(4R)$ while for the right-hand side we have

$$\sum_{1 \leq i < j \leq N} \frac{1}{|x_i - x_j|} \geq \sum_{1 \leq i < j \leq k} \frac{1}{|x_i - x_j|} \geq \frac{k(k-1)}{2} \frac{1}{2R}.$$

As a direct consequence of Theorem 3.2, we obtain

Proposition 3.7. *It holds $\overline{C}(\rho) = 0$ if and only if $\|\rho\| \leq 1/N$.*

Proof. Assume first that ρ satisfies $\|\rho\| \leq 1/N$ and let $\psi \in \mathcal{A}$. By fixing $x_1 = x$ and letting x_2, x_3, \dots, x_N tend to infinity in different directions in the inequality

$$\frac{1}{N} \sum_{i=1}^{i=N} \psi(x_i) \leq c(x),$$

we infer that

$$\psi(x) + (N-1)\psi_\infty \leq 0 \quad \forall x \in \mathbb{R}^d.$$

In particular, by sending $|x|$ to infinity, we deduce that $\psi_\infty \leq 0$. Therefore

$$\int \psi d\rho + (1 - \|\rho\|)\psi_\infty \leq \psi_\infty(1 - N\|\rho\|) \leq 0 \quad \forall \psi \in \mathcal{A}.$$

By (3.3), we are led to $\overline{C}(\rho) \leq 0$, thus $\overline{C}(\rho) = 0$ whenever $\|\rho\| \leq 1/N$.

Let us prove now the converse implication and take an element $\rho \in \mathcal{P}^-$ such that $\overline{C}(\rho) = 0$. By (3.3) for every $\psi \in \mathcal{B}$ we have

$$\int \psi d\rho + (1 - \|\rho\|)\psi_\infty \leq 0.$$

In particular, taking as ψ the function ψ_R of Example 3.6, we have

$$\frac{N-1}{4R}\rho(B_R) - \frac{1}{4R}\rho(B_R^c) - (1 - \|\rho\|)\frac{1}{4R} \leq 0,$$

so that

$$(N-1)\rho(B_R) \leq \rho(B_R^c) + 1 - \|\rho\|.$$

Letting $R \rightarrow +\infty$ gives

$$(N-1)\|\rho\| \leq 1 - \|\rho\|$$

from which $\|\rho\| \leq 1/N$. □

3.1. A weak formulation for dual potentials. The initial motivation of this subsection is to achieve the computation of $\overline{C}(\rho)$ through the formula (3.3) when ρ has a finite support, that is of the kind $\rho = \sum_1^K \alpha_i \delta_{a_i}$ where the $a_i \in \mathbb{R}^d$ are distinct, $\alpha_i \geq 0$ and $\sum \alpha_i \leq 1$. As in Example 3.9 below, we wish to reduce the computation of the supremum in (3.3) to solving a finite dimensional linear programming problem where the unknown vector involved $y \in \mathbb{R}^{K+1}$ is defined by $y_i = \psi(a_i)$ for $1 \leq i \leq K$ and $y_{K+1} = \psi_\infty$. The linear constraints on the components y_i are deduced simply from the overall inequalities in \mathcal{A} (or \mathcal{B}) by restricting them to the support of $\rho^{N\otimes}$.

Then the following issue arises naturally: can we conversely pass from an inequality holding $\rho^{N\otimes}$ almost everywhere to the overall inequality as required in Theorem 3.2? Following the notation introduced in Remark 3.5, we can answer this question through the following weak formulation of the dual problem.

Proposition 3.8. *Let $\rho \in \mathcal{P}^-(\mathbb{R}^d)$ and let $\tilde{\rho} \in \mathcal{P}(X)$ defined by $\tilde{\rho} = \rho + (1 - \|\rho\|)\delta_\omega$. Then*

$$\overline{C}(\rho) = \sup \left\{ \int_X u d\tilde{\rho} : \frac{1}{N} \sum_{i=1}^N u(x_i) \leq \tilde{c}(x) \quad \tilde{\rho}^{N\otimes} \text{ a.e. } x \in X^N \right\}, \quad (3.8)$$

being the supremum taken on $\mathcal{S}(X)$ or on $C(X)$.

Proof. As the admissible set in the right hand side of (3.8) is larger than the one given by (3.4), we only have to prove that, for every $\rho \in \mathcal{P}^-$, it holds:

$$\overline{C}(\rho) \geq \int_X u d\tilde{\rho} \quad \text{for } u \in \tilde{\mathcal{B}}(X), \quad (3.9)$$

where $\tilde{\mathcal{B}}(X)$ denotes the set of elements $u \in \mathcal{S}(X)$ such that

$$\frac{1}{N} \sum_{i=1}^N u(x_i) \leq \tilde{c}(x) \quad \tilde{\rho}^{N\otimes} \text{ a.e. } x \in X^N. \quad (3.10)$$

In a first step, we assume that:

$$u \in C_0 \oplus \mathbb{R} \quad \text{with} \quad u(x) \geq u_\infty (= u^\infty). \quad (3.11)$$

First we notice that the inequality in (3.10) holds in fact point-wise in $(\text{spt}(\tilde{\rho}))^N$. Indeed, if $x \in (\text{spt}(\tilde{\rho}))^N$ is such that $c(x) < +\infty$, then we may integrate the inequality (3.10) on $\Pi_{i=1}^N B(x_i, r)$, where by convention $B(\omega, r) := \{y \in X : |y| > \frac{1}{r}\}$. Then, by dividing by $\Pi_{i=1}^N \tilde{\rho}(B(x_i, r))$ and sending $r \rightarrow 0$, we deduce from the continuity of u and of the continuity of \tilde{c} at x that

$$\frac{1}{N} \sum_{i=1}^{i=N} u(x_i) \leq \tilde{c}(x).$$

Take $\varepsilon > 0$. By the lower semicontinuity of $\tilde{c}(x) - \frac{1}{N} \sum_i u(x_i)$, the subset

$$\left\{ x \in X^N : \frac{1}{N} \sum_{i=1}^N u(x_i) < \tilde{c}(x) + \varepsilon \right\}$$

is an open neighborhood of $(\text{spt}(\rho))^N$. Therefore we may choose an open subset $\Omega_\varepsilon \subset X$ such that:

$$\text{spt}(\tilde{\rho}^{N \otimes}) \subset (\Omega_\varepsilon)^N, \quad \frac{1}{N} \sum_{i=1}^N u(x_i) < \tilde{c}(x) + \varepsilon \text{ for all } x \in (\Omega_\varepsilon)^N.$$

Let us now define:

$$u_\varepsilon(z) := \begin{cases} u(z) & \text{if } z \in \Omega_\varepsilon \\ u_\infty & \text{if } z \in X \setminus \Omega_\varepsilon. \end{cases}$$

Then by (3.11), u_ε belongs to $S(X)$. Furthermore it satisfies the overall inequality deduced from (3.4) replacing \tilde{c} by $\tilde{c} + \varepsilon$. We are now in position to prove (3.9): choose a sequence (P_n) in $\mathcal{P}(R^{Nd})$ such that $\pi_1^\# P_n = \rho_n \xrightarrow{*} \rho$ and

$$\overline{C}(\rho) = \lim_n C(\rho_n) = \lim_n \int \tilde{c}(x) P_n(dx).$$

We obtain

$$\begin{aligned} \overline{C}(\rho) &= \lim_n \int_{X^N} \tilde{c}(x) P_n(dx) \geq \lim_n \inf \int_{X^N} \sum_{i=1}^N \frac{u_\varepsilon(x_i)}{N} P_n(dx) - \varepsilon \\ &\geq \lim_n \inf \int_X u_\varepsilon d\rho_n - \varepsilon \\ &\geq \int_X u_\varepsilon d\tilde{\rho} - \varepsilon, \end{aligned}$$

where in the last line we exploit the lower semicontinuity of u_ε and the (tight) convergence $\rho_n \rightarrow \tilde{\rho} = \rho + (1 - \|\rho\|)\delta_\omega$. We conclude the proof of (3.9) by noticing that $u_\varepsilon = u$ a.e. ($u_\varepsilon = u$ on $\text{spt}(\rho) \cup \{\omega\}$).

In a second step, we remove the assumption that $u(x) \geq u_\infty$. Assume first that $\|\rho\| < 1$, then $\tilde{\rho}$ has a positive mass on ω and condition (3.10) implies then that, for every $k \in \{1, \dots, N\}$:

$$\frac{1}{N} \left(\sum_{i=1}^k u(x_i) + (N-k)u_\infty \right) \leq \tilde{c}_k(x_1, x_2, \dots, x_k) \quad \tilde{\rho}^{k \otimes} \text{ a.e. } (x_1, \dots, x_k) \in X^k$$

Since $\tilde{c}_k(x_1, x_2, \dots, x_k) \leq \tilde{c}(x)$ for every $x \in X$, by setting $v = \sup\{u, u_\infty\}$, we obtain a new continuous function which still satisfies (3.10) and such that

$$\int_X v d\tilde{\rho} \geq \int_X u d\tilde{\rho}.$$

It is then enough to apply the first step to v . If $\|\rho\| = 1$, we simply apply the construction of step 1 changing u_ε into

$$u_\varepsilon(z) := \begin{cases} u(z) & \text{if } z \in \Omega_\varepsilon \\ \inf_X u & \text{if } z \in X \setminus \Omega_\varepsilon \end{cases}.$$

As now $\tilde{\rho}$ has no mass on ω , we still have that $u_\varepsilon = u \tilde{\rho}$ a.e.

Eventually, we drop the continuity assumption by approaching a lower semicontinuous function $u \in \tilde{\mathcal{B}}(X)$ by a sequence of continuous functions (u_n) on X such that:

$$u_{n+1} \geq u_n, \quad \sup_n u_n = u.$$

Clearly each u_n satisfies the constraint (3.10) so that

$$\bar{C}(\rho) \geq \int_X u_n d\tilde{\rho}.$$

The conclusion follows by Beppo-Levi's (monotone convergence) Theorem. \square

Example 3.9. Let $a_1, a_2, a_3 \in \mathbb{R}^3$. Our aim is to compute

$$\bar{C}(\alpha_1 \delta_{a_1} + \alpha_2 \delta_{a_2} + \alpha_3 \delta_{a_3}) := f(\alpha_1, \alpha_2, \alpha_3)$$

as a function defined on the simplex

$$Q := \left\{ \alpha \in \mathbb{R}^3 : \alpha_i \geq 0, \sum_i \alpha_i \leq 1 \right\}.$$

In order to lighten the calculations, we assume that

$$|a_1 - a_2| = |a_2 - a_3| = |a_1 - a_3| = 1$$

and we restrict ourselves to the case $N = 3$, where the cost can be written

$$c(x) = \sum_{1 \leq i < j \leq 3} \frac{1}{|x_i - x_j|} = \frac{1}{|x_1 - x_2|} + \frac{1}{|x_1 - x_3|} + \frac{1}{|x_2 - x_3|}.$$

Owing to the representation formula (3.8), we obtain:

$$f(\alpha_1, \alpha_2, \alpha_3) = \sup \left\{ \begin{array}{l} \sum_{i=1}^3 \alpha_i y_i + (1 - \sum_j \alpha_j) y_4 : \frac{y_1 + y_2 + y_3}{3} \leq 3 \\ y_k + 2y_4 \leq 0, \quad 1 \leq k \leq 3, \quad \frac{y_k + y_l + y_4}{3} \leq 1, \quad 1 \leq k < l \leq 3 \end{array} \right\}$$

where y_i stands for the value of $u(a_i)$ for $i \in \{1, 2, 3\}$ while $y_4 = u(\omega)$. Rewritten in terms of the nonnegative unknowns $x_4 = y_4$ and $x_i = 2x_4 - y_i$ for $i \in \{1, 2, 3\}$, we are led to a classic linear programming problem:

$$f(\alpha_1, \alpha_2, \alpha_3) = \sup \left\{ \left(3 \sum_j \alpha_j - 1 \right) x_4 - \sum_{i=1}^3 \alpha_i x_i : x \geq 0, Ax \leq b \right\},$$

being

$$A = \begin{pmatrix} 0 & -1 & -1 & 3 \\ -1 & 0 & -1 & 3 \\ -1 & -1 & 0 & 3 \\ -1 & -1 & -1 & 6 \end{pmatrix}, \quad b = \begin{pmatrix} 3 \\ 3 \\ 3 \\ 9 \end{pmatrix}$$

It turns out that, for $\alpha \in [0, \frac{1}{3}]^3$, only three vertices are involved in the feasible set, namely $(0, 0, 0, 0)$, $(0, 0, 0, 1)$ and $(3, 3, 3, 3)$. We find

$$f(\alpha) = \begin{cases} \gamma \left(\sum_{j=1}^3 \alpha_j \right) & \text{if } \alpha \in [0, \frac{1}{3}]^3 \\ +\infty & \text{otherwise,} \end{cases} \quad \text{with } \gamma(s) := \begin{cases} 0 & \text{if } s \leq \frac{1}{3} \\ 3s - 1 & \text{if } \frac{1}{3} \leq s \leq \frac{2}{3} \\ 3(2s - 1) & \text{if } \frac{2}{3} \leq s \leq 1. \end{cases}$$

Notice that here the function $\bar{C}(\rho)$, as a function of $\|\rho\|$, is not differentiable at $\|\rho\| \in \{\frac{1}{3}, \frac{2}{3}\}$. This seems to be a general fact when considering measures ρ supported by a set of M points, more precisely if $\|\rho\| = 1$, we expect the function $t \mapsto \bar{C}(t\rho)$ to be non-differentiable for fractional masses $t = \frac{k}{M}$.

3.2. Optimality primal-dual conditions. By exploiting Theorem 3.2 and Theorem 2.3 (in particular (2.7) and (3.3)), we can deduce necessary and sufficient conditions for optimality. It is convenient to introduce, for every $k \in \{1, 2, \dots, N\}$ and $\varphi \in C_0$:

$$M_k(\varphi) = \sup \left\{ \frac{1}{k} \sum_{i=1}^k \varphi(x_i) - c_k(x_1, \dots, x_k) \right\} \quad (3.12)$$

Lemma 3.10. *The following properties hold:*

i) *The functional $M_k(\varphi)$ is convex and 1-Lipschitz on C_0 . Moreover*

$$\lim_{t \rightarrow +\infty} \frac{M_k(t\varphi)}{t} = M_1(\varphi) = \sup \varphi. \quad (3.13)$$

ii) *For every $\varphi \in C_0$ and $N \in \mathbb{N}^*$, we have:*

$$M_1\left(\frac{\varphi}{N}\right) \leq \dots \leq M_k\left(\frac{k\varphi}{N}\right) \leq M_{k+1}\left(\frac{(k+1)\varphi}{N}\right) \leq \dots \leq M_N(\varphi). \quad (3.14)$$

iii) *For every $k \in \mathbb{N}^*$ and $\psi \in C_0$, it holds*

$$M_k(\psi) = M_k(\psi_+) . \quad (3.15)$$

Proof. Let us start to prove i). The convexity property is straightforward since M_k is a supremum of affine continuous functions. On the other hand, for every φ_1, φ_2 in C_0 , we obviously have:

$$M_k(\varphi_2) \leq M_k(\varphi_1) + \sup(\varphi_2 - \varphi_1) \leq M_k(\varphi_1) + \|\varphi_2 - \varphi_1\|.$$

Let us now identify the recession function of M_k that is

$$M_k^\infty(\varphi) := \lim_{t \rightarrow +\infty} \frac{M_k(t\varphi)}{t}.$$

As $M_k(\varphi) \leq \sup \varphi$, we clearly have $M_k^\infty(\varphi) \leq \sup \varphi$. On the other hand, for every $x = (x_i) \in (\mathbb{R}^d)^k$ and $t > 0$ it holds

$$\frac{M_k(t\varphi)}{t} \geq \frac{1}{k} \sum_{i=1}^k \varphi(x_i) - \frac{1}{t} c_k(x),$$

so that, after sending $t \rightarrow +\infty$ and then optimizing with respect to x , we get the converse inequality thus (3.13).

We prove now *ii*). Let $k \in \{1, 2, \dots, N-1\}$ and $\varphi \in C_0$. Then, for every $x = (x_1, x_2, \dots, x_k, x_{k+1}) \in (\mathbb{R}^d)^{k+1}$, it holds:

$$\begin{aligned} M_{k+1}\left(\frac{(k+1)\varphi}{N}\right) &\geq \frac{1}{N} \left(\sum_{i=1}^k \varphi(x_i) + \varphi(x_{k+1}) \right) - c_{k+1}(x) \\ &\geq \frac{1}{k} \left(\sum_{i=1}^k \frac{k\varphi(x_i)}{N} \right) - c_k(x_1, x_2, \dots, x_k), \end{aligned}$$

where in the first line we use the definition (3.12), while in the second line we send x_{k+1} to infinity taking into account that $\varphi(\omega) = 0$. Finally, optimizing with respect to x_1, x_2, \dots, x_k gives the desired inequality (3.14).

Let us finally prove *iii*). The inequality $M_k(\psi) \leq M_k(\psi_+)$ is trivial. To prove the converse inequality, we observe that for every x_1, x_2, \dots, x_k in \mathbb{R}^d , it holds

$$\frac{1}{k} \sum_{i=1}^k \psi_+(x_i) - c_k(x_1, \dots, x_k) \leq \frac{1}{k} \sum_{i=1}^k \psi(y_i) - \tilde{c}_k(y_1, \dots, y_k) \leq M_k(\psi),$$

where $y_i = x_i$ whenever $\psi(x_i) \geq 0$ whereas $y_i = \omega$ otherwise, being \tilde{c}_k the natural extension of c_k to $(\mathbb{R}^d \cup \{\omega\})^k$. One readily checks that $c_k(x_1, \dots, x_k) \geq \tilde{c}_k(y_1, \dots, y_k)$ while $\sum_{i=1}^k \psi_+(x_i) \leq \sum_{i=1}^k \psi(y_i)$ since $\psi(\omega) = 0$. \square

From now on, we will use for $\bar{C}(\rho)$ (resp. for $\mathcal{C}_k(\rho_k)$) given by (3.3) (resp.(2.5)) the duality formulae rewritten in a condensed form as follows.

Proposition 3.11. *For every $\rho \in \mathcal{P}^-$, the following equalities hold:*

$$\bar{C}(\rho) = \sup_{\varphi \in C_0} \left\{ \int \varphi d\rho - M_N(\varphi) \right\}. \quad (3.16)$$

In other words, \bar{C} is the Fenchel conjugate of M_N in the duality between C_0 and the space of bounded measures. In addition, for every $k \leq N$, we have

$$\mathcal{C}_k(\rho_k) = \sup_{\varphi \in C_0} \left\{ \int \varphi d\rho_k - M_k(\varphi) \|\rho_k\| \right\}. \quad (3.17)$$

Proof. For (3.16), we use the first equality in (3.3) with the change of variables $\varphi = \psi - \psi_\infty$, taking into account that $\psi \in \mathcal{A}$ is equivalent to $\psi_\infty \leq -M_N(\varphi)$. For (3.17), it is enough to apply (3.16) replacing N by k and ρ by the probability $\frac{\rho}{\|\rho\|}$. \square

By (3.15), the suprema in (3.16) and (3.17) are unchanged when they are restricted to nonnegative functions $\varphi \in C_0$, and thus

$$\bar{C}(\rho) = \sup_{\varphi \in C_0, \varphi \geq 0} \left\{ \int \varphi d\rho - M_N(\varphi) \right\}.$$

As a consequence we recover that \bar{C} is non-decreasing on \mathcal{P}^- . Moreover an optimal φ (if it exists) or any maximizing sequence (φ_n) can be assumed to be nonnegative.

Theorem 3.12. *Let $\rho \in \mathcal{P}^-$ such that $\|\rho\| > 1/N$. Let $\{\rho_k\}$ be a decomposition such that*

$$\sum_{k=1}^N \frac{k}{N} \rho_k = \rho, \quad \sum_{k=1}^N \|\rho_k\| \leq 1.$$

Then $\{\rho_k\}$ is optimal in (2.7) and φ is optimal in (3.16) (respectively (φ_n) is a maximizing sequence) if and only if the three following conditions hold:

- i) $\sum_{k=1}^N \|\rho_k\| = 1$,
- ii) For all k , $\frac{k\varphi}{N}$ is optimal (resp. $\frac{k\varphi_n}{N}$ is a maximizing sequence) in (3.17)
- iii) $M_k(\frac{k\varphi}{N}) = M_N(\varphi)$ (resp. $M_N(\varphi_n) - M_k(\frac{k\varphi_n}{N}) \rightarrow 0$) holds whenever it exists $l \leq k$ such that $\|\rho_l\| > 0$.

Proof. For any admissible pair $(\{\rho_k\}, \varphi)$, we have

$$\sum_k \mathcal{C}_k(\rho_k) \geq \int \varphi d\rho - M_N(\varphi).$$

Thus the optimality happens as soon the previous inequality becomes an equality. We compute:

$$\begin{aligned} \sum_k \mathcal{C}_k(\rho_k) - \left(\int \varphi d\rho - M_N(\varphi) \right) &= \sum_k \left(\mathcal{C}_k(\rho_k) - \int \frac{k\varphi}{N} d\rho_k + M_k\left(\frac{k\varphi}{N}\right) \|\rho_k\| \right) \\ &\quad + \sum_k \left(M_N(\varphi) - M_k\left(\frac{k\varphi}{N}\right) \right) \|\rho_k\| \quad (3.18) \\ &\quad + M_N(\varphi) \left(1 - \sum_k \|\rho_k\| \right). \end{aligned}$$

By (3.17) and (3.14), we discover that the right hand side of (3.18) consists of the sum of three nonnegative terms. Thus the left hand side vanishes if and only if all these three terms vanish that is to say i), ii) and iii) hold simultaneously. Note that for iii) we use the monotonicity property (3.14) allowing to pass from index l to any $k \geq l$ and Remark 3.13 where we noticed that $M_N(\varphi) > 0$ (resp. $\liminf_{n \rightarrow \infty} M_N(\varphi_n) > 0$ in case of a maximizing sequence (φ_n)). \square

Remark 3.13. Any optimal φ satisfies $M_N(\varphi) > 0$ since otherwise, by (3.12), the inequalities $\sup \varphi = NM_1(\frac{\varphi}{N}) \leq NM_N(\varphi) \leq 0$ would imply that

$$\overline{C}(\rho) = \int \varphi d\rho - M_N(\varphi) \leq (N\|\rho\| - 1)M_N(\varphi) = 0$$

which is excluded since $\overline{C}(\rho) > 0$ if $\|\rho\| > 1/N$ (see Proposition 3.7). In the same way, if (φ_n) is an optimal sequence, we infer that $\liminf_{n \rightarrow \infty} M_N(\varphi_n) > 0$.

Remark 3.14. Note that, in Theorem 3.12, the condition $\sum_{k=1}^N \|\rho_k\| = 1$ holds for any $\{\rho_k\}$ optimal in (3.16) since there always exists a maximizing sequence (φ_n) for the dual problem. Next we observe that, if \bar{k} denotes the integer part of $N\|\rho\|$, then the equality $N\|\rho\| = \sum_{k=1}^N k\|\rho_k\|$ and $\sum_{k=1}^N \|\rho_k\| = 1$ imply that there exist at least two integers $l_- \leq \bar{k} \leq l_+$ such that $\|\rho_{l_\pm}\| > 0$. Accordingly the assertion iii) of Theorem 3.12 includes all values $k > N\|\rho\| - 1$.

4. EXISTENCE OF A LIPSCHITZ POTENTIAL FOR THE RELAXED COST

The main result of this Section is the existence of an optimal potential for the relaxed cost $\bar{C}(\rho)$. Such an existence result is already known for $\|\rho\| = 1$ under a suitable low concentration assumption on the probability ρ (see [4], Theorem 3.6 or [7, section §6] for the sharp constant). More precisely, for every $\rho \in \mathcal{P}^-$, we define

$$K(\rho) = \sup \{ \rho(\{x\}) : x \in \mathbb{R}^d \}.$$

Then if $K(\rho) < \frac{1}{N}$, it is shown in [4, 7] that there exists an optimal continuous bounded Lipschitz potential $u \in \mathcal{B}$.

As a preamble, we prove that in fact this optimal potential u can be chosen in the subclass \mathcal{A} , i.e. u is constant at infinity.

Proposition 4.1. *Let $\rho \in \mathcal{P}$ and let $u \in \mathcal{B}$ be an upper bounded optimal potential for ρ . Then $\tilde{u} := \max\{u, u^\infty\}$ is still an optimal potential for ρ . In particular if u is continuous (resp. Lipschitz continuous), the optimal potential \tilde{u} belongs to \mathcal{A} (resp. to $\mathcal{A} \cap \text{Lip}$).*

Proof. It is enough to check that \tilde{u} is admissible which follows from Lemma 3.1. \square

Now we are going to extend this existence and regularity result to sub-probabilities under the following assumption on ρ :

$$\|\rho\| < 1, \quad \exists \delta > 0 : \bar{C}((1 + \delta)\rho) < +\infty \quad (4.1)$$

Theorem 4.2. *Let $\rho \in \mathcal{P}^-$ satisfying (4.1) for a given $\delta > 0$. Then there exists a Lipschitz optimal potential $u \in C_0 \oplus \mathbb{R}$ solving (3.3). Furthermore any solution to (3.3) coincides with a Lipschitz one on the support of ρ .*

Remark 4.3. The finiteness condition in (4.1) is fulfilled in particular if the concentration satisfies $K(\rho) < \frac{1}{N}$. Indeed, we may choose δ and a smooth density measure ν so that $(1 + \delta)\rho + \nu$ is a probability measure with a concentration still strictly lower than $\frac{1}{N}$, thus with finite cost (from [4, 7]). Then by applying Corollary 3.4, we infer that

$$\bar{C}((1 + \delta)\rho) \leq \bar{C}((1 + \delta)\rho + \nu) = C((1 + \delta)\rho + \nu) < +\infty.$$

On the other hand, by inspecting the proof of Theorem 4.2, we can see that the Lipschitz constant estimate for the optimal potential u depends only on the upper bound obtained in (4.14). Thus at the end we may control the Lipschitz constant of u by the positive slope coefficient $\frac{1}{\delta} (\bar{C}((1 + \delta)\rho) - (1 + \delta)\bar{C}(\rho))$.

The proof of Theorem 4.2 is quite involved and is given in the remaining part of this Section. First we need to fix some notation and give some preliminary results which are gathered in the next subsection.

4.1. Preliminary results. We recall the expression (3.16) for $\bar{C}(\rho)$ that we are using. The existence of an optimal potential u amounts to finding a function $\varphi \in C_0$ such that

$$\bar{C}(\rho) = I_N(\varphi) \quad \text{where} \quad I_N(\varphi) := \int \varphi d\rho - M_N(\varphi) \quad (4.2)$$

where we recall

$$M_N(\varphi) = \sup \left\{ \frac{1}{N} \sum_{i=1}^N \varphi(x_i) - c_N(x_1, \dots, x_N) : x_i \in \mathbb{R}^d \right\}$$

We notice that the definition of $M_N(\varphi)$ above can be obviously extended to any upper bounded Borel function. Accordingly we have very useful properties which are given in the two next Lemmas.

Lemma 4.4. *Let $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$ an upper bounded Borel function and set $\varphi^\infty := \limsup_{|x| \rightarrow +\infty} \varphi(x)$. Then the following inequalities hold:*

$$\frac{1}{N} \sup \varphi + \frac{N-1}{N} \varphi^\infty \leq M_N(\varphi) \leq \sup \varphi. \quad (4.3)$$

$$\frac{1}{N} \varphi^\infty + M_{N-1} \left(\frac{N-1}{N} \varphi \right) \leq M_N(\varphi). \quad (4.4)$$

Proof. The inequality $M_N(\varphi) \leq \sup \varphi$ is trivial. On the other hand, it holds for every $x = (x_i)$ in $(\mathbb{R}^d)^N$:

$$M_N(\varphi) \geq \frac{\varphi(x_1)}{N} - \sum_{j=2}^N \frac{1}{|x_1 - x_j|} + \left(\frac{1}{N} \sum_{i=2}^N \varphi(x_i) - c_{N-1}(x_2, \dots, x_N) \right)$$

By sending all points x_i (with $i \geq 2$) to infinity and then taking the supremum in x_1 , we deduce the first inequality in (4.3). On the opposite, if we send first x_1 to infinity and then optimize with respect to all x_i with $i \geq 2$, we get (4.4) \square

A consequence of (4.3) is that for elements $\varphi \in C_0^+$, $M_N(\varphi)$ is equivalent to the uniform norm. In the sequel we will denote

$$\Delta_N(\varphi) := M_N(\varphi) - M_{N-1} \left(\frac{N-1}{N} \varphi \right). \quad (4.5)$$

By (3.14), we have $\Delta_N(\varphi) \geq 0$ for every $\varphi \in C_0$. Now if φ is a nonnegative element of C_b , in order to show that φ belongs to C_0 it is enough to verify that $\Delta_N(\varphi) = 0$ (just by applying (4.4)).

Lemma 4.5. *Let $\varphi_n : \mathbb{R}^d \rightarrow \mathbb{R}$ be a family of Borel functions such that*

$$\varphi_{n+1} \geq \varphi_n, \quad \varphi := \sup_n \varphi_n \leq C,$$

where C is a suitable constant. Then, for every $k \in \mathbb{N}$, it holds

$$\lim_{n \rightarrow \infty} M_k(\varphi_n) = \sup_n M_k(\varphi_n) = M_k(\varphi).$$

Proof. Clearly $M_k(\varphi_n) \leq M_k(\varphi_{n+1}) \leq M_k(\varphi)$, so that $\lim_n M_k(\varphi_n) \leq M_k(\varphi)$. On the other hand, since $\varphi_n \rightarrow \varphi$ pointwise, we have for every $x = (x_i) \in (\mathbb{R}^d)^k$:

$$\liminf_n M_k(\varphi_n) \geq \lim_n \frac{1}{k} \sum_{i=1}^k \varphi_n(x_i) - c_k(x) = \frac{1}{k} \sum_{i=1}^k \varphi(x_i) - c_k(x),$$

hence $\liminf_n M_k(\varphi_n) \geq M_k(\varphi)$ by optimizing with respect to x . \square

Next, for every upper bounded Borel function φ , we introduce the new function:

$$[M_N \varphi](x) := \sup \left\{ \frac{1}{N} \sum_{i=1}^N \varphi(x_i) - c_N(x_1, \dots, x_N) : x_1 = x, (x_2, \dots, x_N) \in (\mathbb{R}^d)^{N-1} \right\}.$$

By construction, it holds $M_N(\varphi) = \sup\{[M_N \varphi](x) : x \in \mathbb{R}^d\}$. It turns out that, for $\varphi \in C_0$, the limit of $[M_N \varphi]$ at infinity is nothing else but $M_{N-1} \left(\frac{N-1}{N} \varphi \right)$ (see

the Lemma 4.8 hereafter). A key argument in the proof of Theorem 4.2 is the introduction of the regularization of φ defined as follows:

$$\hat{\varphi}(x) = \varphi(x) + N \left(M_{N-1} \left(\frac{N-1}{N} \varphi \right) - [M_N \varphi](x) \right) \quad (4.6)$$

It is easy to check that $\hat{\varphi}$ can be rewritten in the following form

$$\hat{\varphi}(x) = \inf_{x_2, x_3, \dots, x_N} \left\{ N c_N(x, x_2, \dots, x_N) - \sum_{i=2}^N \varphi(x_i) \right\} + N M_{N-1} \left(\frac{N-1}{N} \varphi \right). \quad (4.7)$$

The next fundamental Lipschitz estimate highlights the regularization effect of the map $\varphi \mapsto \hat{\varphi}$.

Proposition 4.6. *For every $R > 0$, there exists a constant $\gamma_N(R)$ such that:*

$$\{\hat{\varphi} : \varphi \in C_0, \varphi \leq R\} \subset Lip_{\gamma_N(R)}(\mathbb{R}^d). \quad (4.8)$$

Proof. Let $\varphi \in C_0$. Then the infimum appearing in (4.7) is non positive since we may take x_2, \dots, x_N arbitrarily away from x and from each other. Therefore we have:

$$\hat{\varphi} \leq N M_{N-1} \left(\frac{N-1}{N} \varphi \right)$$

We can deduce from this a crucial estimate: let $x \in \mathbb{R}^d$ and let $\varepsilon > 0$; then it exists $\eta = \eta(\varepsilon) > 0$ such that every $\bar{x}_2, \dots, \bar{x}_N$ realizing almost $\hat{\varphi}(x)$ in the sense that

$$N c_N(x, \bar{x}_2, \dots, \bar{x}_N) - \sum_{i=2}^N \varphi(\bar{x}_i) \leq \hat{\varphi}(x) - N M_{N-1} \left(\frac{N-1}{N} \varphi \right) + \varepsilon \quad (4.9)$$

must be at least at a distance η from x , that is:

$$|x - \bar{x}_i| \geq \eta, \quad i = 2, \dots, N. \quad (4.10)$$

To check it, we simply observe that the right hand side of (4.9) is not larger than ε . Thus, for every $i \in \{2, \dots, N\}$, we have

$$\varepsilon \geq N c_N(x, \bar{x}_2, \dots, \bar{x}_N) - \sum_{i=2}^N \varphi(\bar{x}_i) \geq N \frac{1}{|x - \bar{x}_i|} - (N-1)R$$

from which the inequality (4.10) follows for any $\eta(\varepsilon) \leq \frac{N}{\varepsilon + (N-1)R}$. In particular, we may take $\eta := \frac{N}{1 + (N-1)R}$ provided $\varepsilon \in (0, 1]$.

We may now obtain the Lipschitz estimates for $\hat{\varphi}$. Let $x \in \mathbb{R}^d$ and let y be such that $|y - x| \leq \frac{\eta}{4}$. Then, for every $\varepsilon \leq 1$ we choose \bar{x}_i for $i \in \{2, \dots, N\}$ which almost realize $\hat{\varphi}(x)$ in the sense of (4.9). In view of (4.7), we may use the \bar{x}_i 's to majorize $\hat{\varphi}(y)$ so that we have:

$$\begin{aligned} \hat{\varphi}(y) - \hat{\varphi}(x) - \varepsilon &\leq N c_N(y, \bar{x}_2, \dots, \bar{x}_N) - \sum_{i=2}^N \varphi(\bar{x}_i) - N c_N(x, \bar{x}_2, \dots, \bar{x}_N) + \sum_{i=2}^N \varphi(\bar{x}_i) \\ &= N \sum_{i=2}^N \left(\frac{1}{|y - \bar{x}_i|} - \frac{1}{|x - \bar{x}_i|} \right) \leq N \sum_{i=2}^N \frac{|x - y|}{|\xi_i - \bar{x}_i|^2} \\ &\leq \frac{N(N-1)16}{9\delta^2} |x - y| \leq \frac{(N-1)(1 + (N-1)R)^2 16}{9N} |x - y|, \end{aligned}$$

where the inequality of the second line, holding for a suitable ξ_i , follows from the Lagrange intermediate value theorem applied to the functions $1/|\cdot - \bar{x}_i|$. This is allowed since $|x - \bar{x}_i| > \eta$ by (4.10) and $|x - y| \leq \eta/4$; in particular $|\xi_i - \bar{x}_i| \geq 3\eta/4$. By passing to the limit $\varepsilon \rightarrow 0$ in the left hand member of the inequalities above, one gets a Lipschitz estimate for $\hat{\varphi}$ in $B(x, \eta/4)$ with a constant independent of x that we denote by $\gamma_N(R)$. Then, clearly we have a global Lipschitz estimate with the same constant. \square

Remark 4.7. The second addendum in (4.7) is estimated as

$$M_{N-1} \left(\frac{N-1}{N} \varphi \right) = \sup_{x_2, \dots, x_N} \left\{ \sum_{i=2}^N \frac{1}{N} \varphi(x_i) - c_{N-1}(x_2, \dots, x_N) \right\} \leq \frac{N-1}{N} R,$$

which is obtained by the fact that c_{N-1} is positive and $\varphi \leq R$. All in all we have $\hat{\varphi} \leq (N-1)R$

We conclude this subsection with a crucial technical result.

Lemma 4.8. *Let $\varphi \in C_0$, $\hat{\varphi}$ defined by (4.6) and $\Delta_N(\varphi)$ defined in (4.5). Then*

- i) $\hat{\varphi}$ belongs to C_0 .*
- ii) The function $\psi = (1 - \frac{1}{N})\varphi + \frac{1}{N}\hat{\varphi}$ satisfies:*

$$M_N(\psi) = M_{N-1} \left(\frac{N-1}{N} \varphi \right). \quad (4.11)$$

$$I_N(\psi) \geq I_N(\varphi) + (1 - \|\rho\|)\Delta_N(\varphi). \quad (4.12)$$

$$\psi \geq \varphi - \Delta_N(\varphi). \quad (4.13)$$

Proof. Let us prove *i)*. By Proposition 4.6, we know already that $\hat{\varphi}$ is Lipschitz continuous. Owing to (4.6), we have only to show that

$$\lim_{|x| \rightarrow +\infty} [M_N \varphi](x) = M_{N-1} \left(\frac{N-1}{N} \varphi \right).$$

First, as $c_N(x_1, x_2, \dots, x_N) \geq c_{N-1}(x_2, \dots, x_N)$, we deduce that:

$$\begin{aligned} [M_N \varphi](x) &\leq \frac{\varphi(x)}{N} + \sup_{(x_2, \dots, x_N)} \left\{ \frac{1}{N} \sum_{i=2}^N \varphi(x_i) - c_{N-1}(x_2, \dots, x_N) \right\} \\ &= \frac{\varphi(x)}{N} + M_{N-1} \left(\frac{N-1}{N} \varphi \right) \end{aligned}$$

Thus, as $\varphi \in C_0$, we have

$$\limsup_{|x| \rightarrow \infty} [M_N \varphi](x) \leq M_{N-1} \left(\frac{N-1}{N} \varphi \right).$$

For the converse inequality, we observe that, for every (x_2, \dots, x_N) , it holds

$$[M_N \varphi](x) \geq \frac{\varphi(x)}{N} - \sum_{j=2}^N \frac{1}{|x - x_j|} + \frac{1}{N} \sum_{i=2}^N \varphi(x_i) - c_{N-1}(x_2, \dots, x_N).$$

hence the conclusion by sending first $|x|$ to infinity and then optimizing with respect to x_2, \dots, x_N .

We prove now *ii*). First the lower bound of ψ given in (4.13) is obtained by recalling that $[M_N\varphi](x) \leq M_N(\varphi)$. Then we infer that:

$$\hat{\varphi}(x) \geq \varphi(x) + N \left(M_{N-1} \left(\frac{N-1}{N} \varphi \right) - M_N(\varphi) \right) = \varphi(x) - N \Delta_N(\varphi).$$

In order to show (4.11), we observe that, by the definition of function $[M_N\varphi]$, we have

$$\sum_{i=1}^N [M_N\varphi](x_i) \geq \sum_{i=1}^N \varphi(x_i) - N c_N(x_1, x_2, \dots, x_N).$$

By applying the definitions of ψ with $\hat{\varphi}$ given by (4.6), it follows that, for every $x = (x_1, x_2, \dots, x_N) \in (\mathbb{R}^d)^N$:

$$\begin{aligned} \sum_i \psi(x_i) &= \sum_i \varphi(x_i) + N M_{N-1} \left(\frac{N-1}{N} \varphi \right) - \sum_i [M_N\varphi](x_i) \\ &\leq N M_{N-1} \left(\frac{N-1}{N} \varphi \right) + N c_N(x) \end{aligned}$$

Therefore

$$\frac{1}{N} \sum_i \psi(x_i) - c_N(x) \leq M_{N-1} \left(\frac{N-1}{N} \varphi \right)$$

and the inequality $M_N(\psi) \leq M_{N-1} \left(\frac{N-1}{N} \varphi \right)$ follows by maximizing with respect to x . The converse inequality holds true since, by (4.13)

$$M_N(\psi) \geq M_N(\varphi) - \Delta_N(\varphi) = M_{N-1} \left(\frac{N-1}{N} \varphi \right).$$

Eventually we infer also (4.12) as a consequence of (4.11) and (4.13). \square

4.2. Proof of Theorem 4.2. We proceed in several steps.

Step 1. Let δ as given by the assumption (4.1). Then there exists $R > 0$ such that:

$$\bar{C}(\rho) = \sup \left\{ I_N(\varphi) : \varphi \in C_0(\mathbb{R}^d, [0, R]) \right\},$$

where $I_N(\varphi)$ is defined in (4.2).

Indeed, by (3.15), we have $M_N(\varphi_+) = M_N(\varphi)$, thus $I_N(\varphi_+) \geq I_N(\varphi)$ for every $\varphi \in C_0$. Therefore the supremum of $I_N(\varphi)$ is unchanged if we restrict to $\varphi \in C_0^+$. On the other hand, for every given $\varepsilon > 0$, we may restrict the supremum to the subclass

$$\mathcal{A}_\varepsilon := \left\{ \varphi \in C_0^+ : I_N(\varphi) \geq \bar{C}(\rho) - \varepsilon \right\}.$$

Since

$$\bar{C}((1+\delta)\rho) \geq (1+\delta) \int \varphi d\rho - M_N(\varphi),$$

we deduce that, for every $\varphi \in \mathcal{A}_\varepsilon$, it holds:

$$\bar{C}((1+\delta)\rho) - (1+\delta)\bar{C}(\rho) \geq \delta M_N(\varphi) - (1+\delta)\varepsilon \geq \frac{\delta}{N} \sup \varphi - (1+\delta)\varepsilon.$$

Therefore $\mathcal{A}_\varepsilon \subset C_0(\mathbb{R}^d, [0, R])$ for small ε , provided

$$R > \frac{N}{\delta} \left(\bar{C}((1+\delta)\rho) - (1+\delta)\bar{C}(\rho) \right). \quad (4.14)$$

Step 2. For every $\varepsilon > 0$, there exists $\psi \in C_0(\mathbb{R}^d, [0, NR])$ such that

$$I_N(\psi) \geq \bar{C}(\rho) - \varepsilon, \quad M_N(\psi) \leq R, \quad \text{Lip}(\psi) \leq \gamma_N(NR). \quad (4.15)$$

The existence of ψ satisfying (4.15) will be derived after designing a suitable sequence (u_n) in C_0 . We start with an element $\varphi_\varepsilon \in C_0(\mathbb{R}^d; [0, R])$ such that $I_N(\varphi_\varepsilon) > \bar{C}(\rho) - \varepsilon$ as given in Step 1. Then we define a sequence (u_n) as follows:

$$u_0 = \varphi_\varepsilon, \quad u_{n+1} = \frac{1}{N} \hat{u}_n + \frac{N-1}{N} u_n.$$

Applying Lemma 4.8 we get

$$I_N(u_{n+1}) \geq I_N(u_n) + (1 - \|\rho\|) \Delta_N(u_n) \quad (4.16)$$

$$u_{n+1} \geq u_n - \Delta_N(u_n) \quad (4.17)$$

$$M_N(u_n) \geq M_{N-1}\left(\frac{N-1}{N} u_n\right) = M_N(u_{n+1}). \quad (4.18)$$

From (4.16) follows that $I_N(u_n)$ is non-decreasing. Since $I_N(\varphi_\varepsilon) \leq I_N(u_n) \leq \bar{C}(\rho)$, its limit satisfies:

$$\bar{C}(\rho) - \varepsilon < \lim_n I_N(u_n) \leq \bar{C}(\rho). \quad (4.19)$$

Now we use the condition $\|\rho\| < 1$ to infer from (4.16) that

$$\sum_{n=1}^{\infty} \Delta_N(u_n) \leq \frac{\varepsilon}{1 - \|\rho\|} < +\infty.$$

Let us denote by $\varepsilon_n := \sum_{k \geq n} \Delta_N(u_k)$ the remainder of the series; we see from (4.17) that $v_n = u_n - \varepsilon_n$ is monotone non-decreasing. Therefore u_n and v_n share the same point-wise limit $u(x)$ which at least is a lower semicontinuous function. Next we can derive in a straightforward way a uniform upper bound for the u_n by applying the monotonicity property (4.18). Indeed, according to the choice $u_0 = \varphi_\varepsilon$ for the initial term which satisfies $\sup u_0 \leq R$, we have

$$\frac{1}{N} \sup u_n \leq M_N(u_n) \leq M_N(u_0) \leq R. \quad (4.20)$$

Then we may apply to (v_n) the continuity property on monotone sequences given in Lemma 4.5 for $k = N - 1$ and $k = N$, noticing that $M_k(u_n) = M_k(v_n) + \varepsilon_n$:

$$M_N(u_n) \rightarrow M_N(u), \quad M_{N-1}\left(\frac{N-1}{N} u_n\right) \rightarrow M_{N-1}\left(\frac{N-1}{N} u\right).$$

It follows that

$$\Delta_N(u) = \lim_n \Delta_N(u_n) = 0.$$

As a consequence of (4.4), we deduce that

$$u^\infty = \limsup_{|x| \rightarrow \infty} u(x) \leq 0.$$

Next, in order to gain the Lipschitz regularity of u , we are going to apply Proposition 4.6 to the sequence (u_n) . By construction, we have $\hat{u}_n - u_n = N(u_{n+1} - u_n)$. Therefore $\hat{u}_n - u_n \rightarrow 0$ and $\hat{u}_n \rightarrow u$ pointwise on \mathbb{R}^d . As a consequence of (4.8) (\hat{u}_n) is equi-Lipschitz with constant $\gamma_N(NR)$. By Arzelá-Ascoli's Theorem, it converges to u uniformly on compact subsets of \mathbb{R}^d . Its limit u satisfies as well $\sup u \leq NR$ and it is Lipschitz continuous with the constant $\gamma_N(NR)$.

Eventually we claim that the function $\psi = u_+$ satisfies the three requirements in (4.15). Indeed, $u^+(\omega) \leq 0$ implies that ψ is an element of $C_0(\mathbb{R}^d; [0, NR])$. It has the same Lipschitz constant $\gamma_N(NR)$. In addition, by Lemma 3.15 and (4.20), we have $M_N(\Psi) = M_N(u) \leq R$. Eventually, by monotone convergence, we have:

$$\lim_n I_N(u_n) = \lim_n \int u_n d\rho - \lim_n M_N(u_n) = \int u d\rho - M_N(u) = I_N(u),$$

and the first condition in Claim (4.15) follows from (4.19).

Step 3. *There exists a sequence (φ_n) in $C_0(\mathbb{R}^d, [0, R])$ and $\varphi \in C_0(\mathbb{R}^d, [0, NR])$ with $\text{Lip}(\varphi) \leq \gamma_N(NR)$ such that*

$$\varphi_{n+1} \geq \varphi_n, \quad I_N(\varphi_n) \rightarrow \bar{C}(\rho), \quad \sup_n \varphi_n = \varphi. \quad (4.21)$$

By applying step 2 for $\varepsilon = \frac{1}{n}$, we obtain a sequence (ψ_n) in $C_0(\mathbb{R}^d; [0, NR])$ with a uniform Lipschitz constant $\gamma_N(NR)$ and such that $I_N(\psi_n) \rightarrow \bar{C}(\rho)$. By Arzelà-Ascoli's Theorem and possibly after passing to a suitable subsequence, we may assume that ψ_n converges uniformly on compact subsets to a Lipschitz continuous $\varphi \in C(\mathbb{R}^d; [0, NR])$. At this point, we would also need a uniform convergence on the whole \mathbb{R}^d in order to conclude that φ vanishes at infinity. To avoid this difficulty, we turn to another sequence in $C_0(\mathbb{R}^d, [0, NR])$, namely (φ_n) defined by

$$\varphi_n := \inf \{ \psi_m : m \geq n \}.$$

Clearly the pointwise convergence $\psi_n \rightarrow \varphi$ implies that φ_n converges increasingly to φ . As $M_N(\varphi_n) \leq M_N(\psi_n)$, we have

$$I_N(\varphi_n) \geq I_N(\psi_n) - r_n, \quad r_n = \int (\psi_n - \varphi_n) d\rho,$$

where $r_n \rightarrow 0$ by dominated convergence. Therefore (φ_n) is a maximizing sequence for (3.16) and by applying the assertion iii) of Theorem 3.12 for $k = N - 1$ (see Remark 3.14), we deduce that

$$M_N(\varphi_n) - M_{N-1} \left(\frac{N-1}{N} \varphi_n \right) \rightarrow 0.$$

Thus, again by the monotonicity property of Lemma 4.5, we are led to the equality

$$M_N(\varphi) - M_{N-1} \left(\frac{N-1}{N} \varphi \right) = 0$$

from which follows that $\varphi^\infty \leq 0$ (see Lemma 4.4). As φ is continuous nonnegative, we conclude that $\varphi \in C_0$ thus (4.21).

Concluding the proof. The φ constructed in Step 3 obviously satisfies (4.2). Indeed, the convergence $\varphi_n \rightarrow \varphi$ is strong in C_0 (as a consequence of Dini's Theorem on the compact set $\mathbb{R}^d \cup \{\omega\}$) and therefore, recalling that the map $M_N : C_0 \rightarrow \mathbb{R}$ is Lipschitz continuous (see Lemma 3.10), it holds $M_N(\varphi_n) \rightarrow M_N(\varphi)$. Thus $u = \varphi - M_N(\varphi)$ is an optimal potential for the dual problem (3.3). Its Lipschitz constant is not larger than $\gamma_N(NR)$ given by Proposition 4.6, being R given in Step 1.

Eventually let be v be another solution to (3.3). Then $v = \tilde{\varphi} - M_N(\tilde{\varphi})$ for an element $\tilde{\varphi} \in C_0$ solving (4.2). Thanks to (4.12), the function $\psi = (1 - \frac{1}{N})\tilde{\varphi} + \frac{1}{N}\widehat{\tilde{\varphi}}$ introduced in Lemma 4.8 satisfies:

$$I_N(\psi) \geq I_N(\tilde{\varphi}) + (1 - \|\rho\|) \Delta_N(\tilde{\varphi}).$$

The optimality of $\tilde{\varphi}$ implies that $I_N(\psi) = I_N(\tilde{\varphi})$ and that $\Delta_N(\tilde{\varphi}) = 0$, thus $\psi \geq \tilde{\varphi}$ thanks to (4.13). It follows that $\psi = \tilde{\varphi} = \hat{\psi}$ holds ρ a.e., hence on $\text{spt}(\rho)$ by continuity. As $\sup \tilde{\varphi} \leq R$ by step 1, then $M_N(\psi) \leq M_N(\tilde{\varphi})$ implies that $\sup \psi \leq NR$ and, by applying (4.8), ψ is Lipschitz with constant $\gamma_N(NR)$ while it coincides with $\tilde{\varphi}$ on $\text{spt}(\rho)$. \square

5. QUANTIZATION OF RELAXED MINIMIZERS

In this Section we focus on the relaxed problem mentioned in the introduction namely

$$\min \left\{ \overline{C}(\rho) - \int V d\rho : \rho \in \mathcal{P}^- \right\}, \quad (5.1)$$

where V is a given potential in C_0 . Note that the infimum above would blow-up to $-\infty$ if V is not upper bounded, as for instance in the case of Coulomb potential. The existence of solutions to (5.1) in \mathcal{P}^- is straightforward as we minimize a convex lower semicontinuous functional on the weakly* compact set \mathcal{P}^- . On the other hand, as the minimum in (5.1) agrees with that of

$$\inf \left\{ C(\rho) - \int V d\rho : \rho \in \mathcal{P} \right\}, \quad (5.2)$$

any solution $\rho \in \mathcal{P}$ to (5.1) is also a solution to (5.2) and vice-versa.

We pay now attention to the set of minimizers

$$\mathcal{S}_V = \left\{ \rho \in \mathcal{P}^- : \rho \text{ solves (5.1)} \right\}.$$

As by (3.16) $\overline{C}(\rho)$ agrees with the Fenchel conjugate of M_N , we may interpret \mathcal{S}_V in the language of convex analysis as the sub-differential of M_N at V , i.e.

$$\mathcal{S}_V = \left\{ \rho \in \mathcal{P}^- : \overline{C}(\rho) - \int V d\rho + M_N(V) \leq 0 \right\}.$$

In particular \mathcal{S}_V is a convex weakly* compact subset of \mathcal{P}^- . Note that in general \mathcal{S}_V is not a singleton as the functional \overline{C} is not strictly convex. Besides we observe that the minimum value of (5.1) is strictly negative unless the positive part of V vanishes. Indeed, by considering competitors ρ such that $\|\rho\| \leq \frac{1}{N}$ (thus $\overline{C}(\rho) = 0$ by Proposition 3.7), we have the following estimate

$$\inf \{(5.1)\} \leq -\frac{1}{N} \sup V^+. \quad (5.3)$$

One of the major questions in the ionization problem, as developed for instance in [13, 14, 22, 23] in a much more complex case, is to determine conditions on the potential V under which (5.1) admits solutions in \mathcal{P} . We give here a sufficient condition.

Theorem 5.1. *Assume that the potential V satisfies the condition*

$$M_N(V) > M_{N-1}\left(\frac{N-1}{N}V\right). \quad (5.4)$$

Then all solutions ρ to (5.1) satisfy $\|\rho\| = 1$, that is $\mathcal{S}_V \subset \mathcal{P}$. Moreover the supremum defining $M_N(V)$ in (3.12) is a maximum.

Proof. Assume that there exists a solution ρ such that $\|\rho\| < 1$. Then, as V is a solution to the dual problem associated with ρ , we may apply the optimality conditions derived in Theorem 3.12. Let $\{\rho_l\}$ be optimal in (2.7). Then by Remark 3.14, we know that it exists at least one index $l \leq N - 1$ such that $\|\rho_l\| > 0$ and therefore, condition iii) is satisfied for $k = N - 1$. Thus $M_N(V) = M_{N-1}(\frac{N-1}{N}V)$, in contradiction with our assumption. For the last statement, we consider a point $\bar{x} \in X^N$ (recall that $X = \mathbb{R}^d \cup \{\omega\}$) such that:

$$M_N(V) = \sup_{x \in (\mathbb{R}^d)^N} \frac{1}{N} \sum_{i=1}^N V(x_i) - c_N(x) = \frac{1}{N} \sum_{i=1}^N V(\bar{x}_i) - \tilde{c}_N(\bar{x}),$$

being \tilde{c}_N the lower semicontinuous extension of c_N to X^N (see (2.1)). Such an optimal \bar{x} exists since we maximize an u.s.c. function on a compact set. If the infimum is not reached in $(\mathbb{R}^d)^N$, that means that $\bar{x}_i = \omega$ for at least one index i for instance $i = N$ and we are led to

$$M_N(V) = \sum_{i=1}^{N-1} V(\bar{x}_i) - \tilde{c}_{N-1}(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_{N-1}) \leq M_{N-1}\left(\frac{N-1}{N}V\right),$$

in contradiction with (5.4). \square

In view of Theorem 5.1, a meaningful question is now to understand what happens when equality $M_N(V) = M_{N-1}(\frac{N-1}{N}V)$ holds. To that aim it is useful to introduce:

$$k_N(V) := \max \left\{ k \in \{1, 2, \dots, N\} : M_k\left(\frac{k}{N}V\right) > M_{k-1}\left(\frac{k-1}{N}V\right) \right\}. \quad (5.5)$$

Here we set by convention $M_0(0) = 0$ so that $k_N(V)$ is well defined if V^+ does not vanish. Otherwise we set $k_N(V) = 0$.

Corollary 5.2. *Let V be a potential in C_0^+ such that:*

$$\beta := \limsup_{|x| \rightarrow +\infty} |x|V(x) > 0.$$

Then the condition (5.4) is satisfied whenever

$$\beta > N(N-1). \quad (5.6)$$

In particular the conclusions of Theorem 5.1 apply in this case.

Proof. To help the reader, we begin with a first step assuming that the supremum in the definition of $M_{N-1}(\frac{N-1}{N}V)$ is reached by a system of $N-1$ points x_1, x_2, \dots, x_{N-1} in \mathbb{R}^d that is

$$M_{N-1}\left(\frac{N-1}{N}V\right) = \frac{1}{N} \sum_{i=1}^{N-1} V(x_i) - c_{N-1}(x_1, \dots, x_{N-1}).$$

Then for every x_N , we have:

$$M_N(V) \geq M_{N-1}\left(\frac{N-1}{N}V\right) + \frac{V(x_N)}{N} - \sum_{i=1}^{N-1} \frac{1}{|x_N - x_i|}. \quad (5.7)$$

Now as (5.6) holds, we can choose $|x_N|$ so large to have

$$\frac{V(x_N)}{N} - \sum_{i=1}^{N-1} \frac{1}{|x_N - x_i|} > 0 \quad (5.8)$$

and (5.4) follows. This proof can be extended to the case where the $N - 1$ points infimum related to $M_{N-1}\left(\frac{N-1}{N}V\right)$ is not attained in $(\mathbb{R}^d)^{N-1}$, by considering instead of $N - 1$ the index $\bar{k} := k_{N-1}(V)$ defined by (5.5). It satisfies:

$$M_{N-1}\left(\frac{N-1}{N}V\right) = M_{N-2}\left(\frac{N-2}{N}V\right) = \dots = M_{\bar{k}}\left(\frac{\bar{k}}{N}V\right) > M_{\bar{k}-1}\left(\frac{\bar{k}-1}{N}V\right)$$

(notice that $\bar{k} \geq 1$ since $\beta > 0$ implies that $V \neq 0$). By applying the last statement of Theorem 5.1 with $N = \bar{k}$, we deduce the existence of a system of \bar{k} points $x_1, x_2, \dots, x_{\bar{k}}$ in \mathbb{R}^d where $\bar{k} \leq N - 1$ such that

$$M_{\bar{k}}\left(\frac{\bar{k}}{N}V\right) = \frac{1}{\bar{k}} \sum_{i=1}^{\bar{k}} V(x_i) - c_{\bar{k}}(x_1, \dots, x_{\bar{k}}).$$

Accordingly the counterpart of the inequality (5.7) is the following

$$\begin{aligned} M_N(V) &\geq M_{\bar{k}}\left(\frac{\bar{k}}{N}V\right) + \sum_{\bar{k} < j \leq N} \frac{V(x_j)}{N} \\ &\quad - \sum_{1 \leq i \leq \bar{k} < j \leq N} \frac{1}{|x_i - x_j|} - \sum_{\bar{k} < j < l \leq N} \frac{1}{|x_j - x_l|}. \end{aligned} \quad (5.9)$$

As (5.9) holds for all x_j with $j > \bar{k}$ and for all x_l with $l > j$, by sending $|x_l| \rightarrow \infty$ and then $|x_j| \rightarrow \infty$ for $\bar{k} < j \leq N - 1$, we are led to

$$M_N(V) - M_{N-1}\left(\frac{N-1}{N}V\right) = M_N(V) - M_{\bar{k}}\left(\frac{\bar{k}}{N}V\right) \geq \frac{V(x_N)}{N} - \sum_{1 \leq i \leq \bar{k}} \frac{1}{|x_i - x_N|},$$

which holds for every $x_N \in \mathbb{R}^d$. The conclusion follows by choosing $|x_N|$ so large to have:

$$\frac{V(x_N)}{N} - \sum_{1 \leq i \leq \bar{k}} \frac{1}{|x_i - x_N|} > 0$$

(note that this condition is weaker than (5.8) if $\bar{k} < N - 1$). \square

Remark 5.3. As a consequence of Theorem 5.1, we obtain that optimal solutions belong to \mathcal{P} as long as V is “large” enough. More precisely, if the positive part of V does not vanish, then there exists a constant $t^* \geq 0$ such that for $Z > t^*$, the potential ZV satisfies (5.4). Indeed, by applying (3.13), we derive that

$$\lim_{Z \rightarrow +\infty} \frac{M_k\left(\frac{k}{N}ZV\right) - M_{k-1}\left(\frac{k-1}{N}ZV\right)}{Z} = \frac{1}{N} \sup V > 0,$$

Moreover, if the potential V is strong enough at infinity, we may even have $t^* = 0$. Indeed by applying Corollary 5.2 to a potential $V \in C_0^+$ satisfying $\beta = +\infty$ (*confining potential*), we obtain that $\mathcal{S}_{tV} \subset \mathcal{P}$ hold for all $t > 0$. Unfortunately we do not know in general if the opposite condition $t < t^*$ implies that $\mathcal{S}_{tV} \cap \mathcal{P}$ is empty. In Example 5.5, we merely show that the latter set is empty if V has compact support and $t < t_*$ for a suitable $t_* \leq t^*$

Remark 5.4. The minimization problem (5.1) can be also studied for potentials V possibly unbounded. In fact an important case, which is beyond the scope of this paper, occurs when $\lim_{|x| \rightarrow \infty} V = -\infty$. In this case the minimum is reached

on probability measures and we observe that, extending the definition of M_N to such potentials, we have a relation with the so called systems of points interactions theory confined by an external potential, since

$$-M_N(-N^2V) = \inf \{ \mathcal{H}_N(x_1, x_2, \dots, x_N) : x_i \in \mathbb{R}^d \}$$

where \mathcal{H}_N is of the form

$$\mathcal{H}_N(x_1, x_2, \dots, x_N) = \sum_{1 \leq i < j \leq N} \ell(|x_i - x_j|) + N \sum_{i=1}^N V(x_i).$$

In such a setting, the asymptotic limit as $N \rightarrow \infty$ is one of the main points of interest of the mathematical physics community (see for instance the recent works [16, 20, 21]). This prompts us to suggest, as a motivation for future works, the study of the asymptotics (as $N \rightarrow \infty$) in the case of a potential vanishing at infinity, like in problem (5.1). In this respect, we mention a forthcoming paper [1].

Example 5.5. (Non existence of an optimal probability) Let $V \in C_0^+$ with compact support and let $R > 0$ such that $\text{spt } V \subset \overline{B_R}$. Then it is easy to check that any solution ρ to (1.1) such that $\|\rho\| = 1$ must satisfy as well $\text{spt } \rho \subset \overline{B_R}$. Indeed, otherwise we can move away the part of such a ρ which lies outside $\overline{B_R}$ letting $\int V d\rho$ invariant and making $C(\rho)$ decrease. For instance we may consider $\rho' = T^\#(\rho)$ where

$$T(x) = k_R(|x|)x \quad \text{with} \quad k_R(x) := \max \left\{ 1, \frac{|x|}{R} \right\}.$$

For such a map we have $|Tx - Ty| \geq |x - y|$ with strict inequality whenever $(x, y) \notin B_R^2$, so that $C(\rho') < C(\rho)$ unless $\text{spt } \rho \subset \overline{B_R}$.

Next by applying a lower bound estimate for $C(\rho)$ in term of the variance of ρ (see Prop 2.2 in [3]), we infer that:

$$C(\rho) \geq \frac{N(N-1)}{4\sqrt{\text{Var}(\rho)}} \geq \frac{N(N-1)}{4R}.$$

On the other hand, by (5.3) and as ρ is optimal, it holds $C(\rho) \leq (1 - \frac{1}{N}) \sup V$. Therefore a solution in \mathcal{P} cannot exist unless the following lowerbound holds for $\sup V$:

$$\frac{N^2}{4R} \leq \sup V.$$

This necessary condition applies of course if we substitute potential V with tV and we deduce that $\mathcal{S}_{tV} \cap \mathcal{P}$ is empty whenever $t < t_*$ where

$$t_* := \frac{N^2}{4R \sup V}.$$

We are now in a position to state the quantization phenomenon we have announced in the Introduction. For every non-vanishing $V \in C_0$, we define:

$$\mathcal{I}_N(V) := \min \{ \|\rho\| : \rho \in \mathcal{S}_V \}. \quad (5.10)$$

The minimum in (5.10) is achieved by the weak* lower semicontinuity of the map $\rho \mapsto \|\rho\|$ and optimal ρ represent elements with minimal norm in \mathcal{S}_V . On the other hand, $\mathcal{I}_N(V)$ depends only on the positive part of V i.e. $\mathcal{I}_N(V) = \mathcal{I}_N(V^+)$.

Theorem 5.6. *Let $V \in C_0$, $N \in \mathbb{N}^*$ and $k_N(V)$ given by (5.5). Then*

$$\mathcal{I}_N(V) = \frac{k_N(V)}{N}.$$

As a consequence, the map $V \in C_0 \mapsto \mathcal{I}_N(V)$ takes values in the finite set

$$\left\{ \frac{k}{N} : 0 \leq k \leq N \right\}.$$

Proof. First we observe that the result is trivial if $k_N(V) = 0$. Indeed in this case, $V^+ \equiv 0$ implies that the minimum in (5.1) vanishes. The minimal set is then reduced to $\rho = 0$ and $\mathcal{I}_N(V) = 0$. We may therefore assume that $k_N(V) \geq 1$. To lighten the notation, let us now set $\bar{k} := k_N(V)$. First we show that $\mathcal{I}_N(V) \leq \bar{k}/N$. By (5.5), we have that $M_{\bar{k}}(\frac{\bar{k}}{N}V) > M_{\bar{k}-1}(\frac{\bar{k}-1}{N}V)$ while, recalling the monotonicity property (3.14), it holds $M_k(\frac{k}{N}V) = M_N(V)$ for every $k \geq \bar{k}$. Let us apply Theorem 5.1 taking instead of $C = C_N$ the \bar{k} multi-marginal energy and choosing $\bar{k}V/N$ as a potential. Therefore it exists a probability $\rho_{\bar{k}}$ such that:

$$C_{\bar{k}}(\rho_{\bar{k}}) - \int \frac{\bar{k}V}{N} d\rho_{\bar{k}} = -M_{\bar{k}}\left(\frac{\bar{k}V}{N}\right).$$

Then we claim that $\rho := \frac{\bar{k}}{N}\rho_{\bar{k}}$ solves (5.1) (i.e. belongs to \mathcal{S}_V). Indeed, by (2.9), we have:

$$\bar{C}(\rho) - \int V d\rho \leq C_{\bar{k}}(\rho_{\bar{k}}) - \int \frac{\bar{k}V}{N} d\rho_{\bar{k}} = -M_{\bar{k}}\left(\frac{\bar{k}V}{N}\right) = -M_N(V).$$

As the mass of ρ is exactly \bar{k}/N , we infer that $\mathcal{I}_N(V) \leq \bar{k}/N$.

Let us prove now the opposite inequality. Let $\rho \in \mathcal{S}_V$ and let $\{\rho_k\}$ be an optimal decomposition for ρ according to (2.7), with

$$\rho = \sum_{k=1}^N \frac{k}{N} \rho_k.$$

By the optimality conditions of Theorem 3.12, it holds $M_k(\frac{k}{N}V) = M_N(V)$ whenever $\|\rho_k\| > 0$. Then we observe that the latter equality cannot hold for $k \leq \bar{k}-1$. Indeed, by the monotonicity property (3.14):

$$M_k\left(\frac{k}{N}V\right) \leq M_{\bar{k}-1}\left(\frac{\bar{k}-1}{N}V\right) < M_{\bar{k}}\left(\frac{\bar{k}}{N}V\right) = M_N(V).$$

Therefore we have $\rho_k = 0$ for every $k \leq \bar{k}-1$. Thus recalling that $\sum_k \|\rho_k\| = 1$ by the optimality conditions (assertion i) of Theorem 3.12):

$$\|\rho\| = \sum_{k=\bar{k}}^N \frac{k}{N} \|\rho_k\| \geq \frac{\bar{k}}{N} \sum_{k=\bar{k}}^N \|\rho_k\| \geq \frac{\bar{k}}{N}.$$

Accordingly we obtain the opposite inequality $\mathcal{I}_N(V) \geq \bar{k}/N$. \square

Remark 5.7. The functional $V \in C_0 \mapsto \mathcal{I}_N(V)$ is lower semicontinuous with respect to the uniform convergence. Indeed if $V_n \rightarrow V$ uniformly and if we take $\rho_n \in \mathcal{S}_{V_n}$ such that $\|\rho_n\| = \mathcal{I}_N(V_n)$, then any weak* limit ρ of a subsequence of (ρ_n) is such that $\rho \in \mathcal{S}_V$ and

$$\mathcal{I}_N(V) \leq \|\rho\| \leq \liminf_n \|\rho_n\| = \liminf_n \mathcal{I}_N(V_n).$$

In general the potential V depends on several charge parameters and takes the form

$$V(x) = \sum_{k=1}^M Z_k V_k(x) \quad Z_k > 0.$$

It is then interesting to analyze the function

$$\mathcal{I}_N(V) = \mathcal{I}_N\left(\sum_{k=1}^M Z_k V_k\right)$$

as a function depending on the Z_k 's. It turns out that this question is a very delicate one which will motivate future work. In case of a single charge parameter $Z > 0$ applied to a given potential $V \in C_0^+$, it is natural to expect that the map $Z \in \mathbb{R}^+ \mapsto \mathcal{I}_N(ZV)$ is a non-decreasing step function encoded by threshold values $0 = t_0 \leq t_1 \leq \dots \leq t_N < t_{N+1} = +\infty$ such that $\mathcal{I}_N(ZV) = \frac{k}{N}$ for $Z \in (t_k, t_{k+1}]$. At present a proof of this fact is available only in the case $N = 2$ where it is a consequence of the fact that the set $\{Z \geq 0 : M_2(ZV/2) > M_1(ZV) = Z \sup V\}$ is an half line.

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